

Customizable Vision System

XG-X Series



Covering Every Aspect of Image Processing With a Single Unit



Meeting All Needs for Image Processing With a Single Unit

This one unit supports various camera connections and image capture methods. It has options perfectly suited for solving a wide-range of problems, so there is no need to change the hardware or software, providing powerful support for solving the problems faced by KEYENCE customers.



Multi-Spectrum Image Capture









Line Scan Cameras

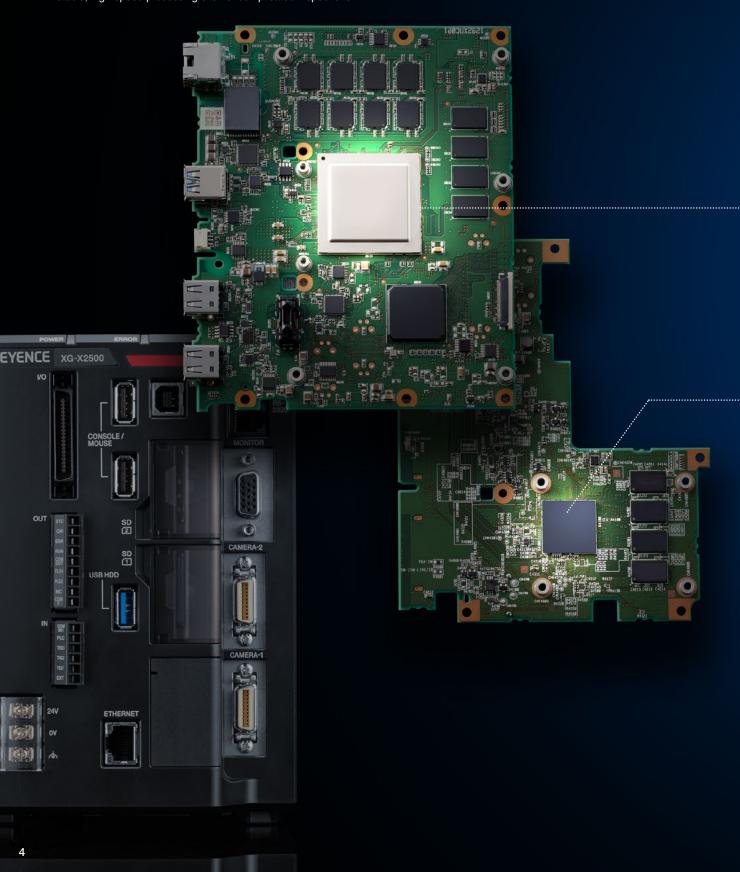


In-Line 3D Inspection



Multi-Core Processors With the Highest Performance in the World Make It Possible to Link and Combine All Cameras and Lighting

Becoming number 1 in application solving requires powerful hardware. Optimising the 14 cores has enabled stable, high-speed processing even of complicated inspections.



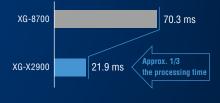
Stable, high-speed processing through parallel processing with 14* cores

DSP + CPU



Abundant processing power is available even with multiple camera connections, including high-resolution 64 megapixel colour cameras, line scan cameras, and 3D inspection cameras. Furthermore, the largest-in-class image memory can store over 28,300 images captured with VGA colour cameras, or approximately 290 images captured with 21 megapixel colour cameras.

21 megapixel colour camera flaw inspection processing speed



* XG-X2700/X2800/X2900 has 14 cores. XG-X2000/X2200/X2500 has 8 cores. XG-X1000/X1200/X1500 has 7 cores.

CPU



DSP + CPU cores

Compared with conventional models



Processing speed

Compared with conventional models



Memory capacity

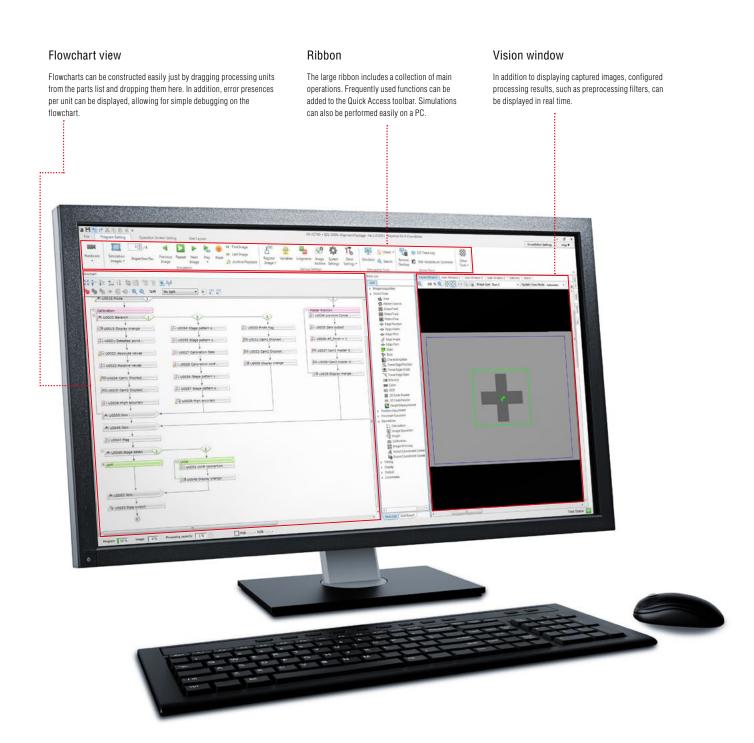
Compared with conventional models



Seamless Creation of Inspection Results with VisionEditor

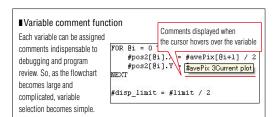
Flowchart programming offers the flexibility to bring your concepts to life.

"XG-X VisionEditor" is software designed for quick development of vision inspection applications, creation of user interfaces, easy debugging, simulations, and more.



Variable processing

A wide range of variables can be defined, including image, positional, linear, numerical, and array-based. Variables are not limited to a single program and can be set for global use.





Variable setting screen

Flexible calculation & processing

Calculations and scripts are also essential in customisation. The XG-X Series allows for over 150 different functions and commands that can be quickly created by dragging functions from the parts list. An auto-complete function and error location display help reduce troubleshooting time due to syntax errors.



Script #N1 = 1 | 10 [0012] .RSLT.W[JOL] :HS #N2 | #N3 | #N3 | #N4 | #N4 | #N5 | #N6 | #N6 | #N7 | #N6 | #N7 | #N7 | #N7 | #N8 | #N7 | #N8 | #N7 | #N8 |

Up to 5000 characters per single calculation

Automatic and interactive command processing

Control commands allow for seamless interaction between the vision system and a machine's controls or PLC. Commands like program switching, image capture, reset, start/stop operation log, changing to a different displayed image, zooming in on a defect based on an inspection result, or saving image data for a certain part failure are all possible. These commands can even be automated as part of the program flowchart, and custom commands can be created to combine specified built-in commands into a single command.

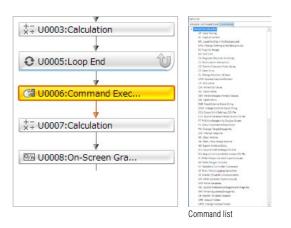
■ Examples of Built-in Commands

System control

Common commands include: program switching, image save, trigger input enable/disable, mode switching (run/stop), reset, write variables, clear history data, export history data, image capture, start/stop operation log

User interaction

Common commands include: open/close dialogue boxes, image switching, image zoom, image scroll, change password, switch user accounts



Advanced Interaction with Vision Controllers

Access interface designed for ease of use

Inspection flows created using VisionEditor can be uploaded to controllers with a single click.

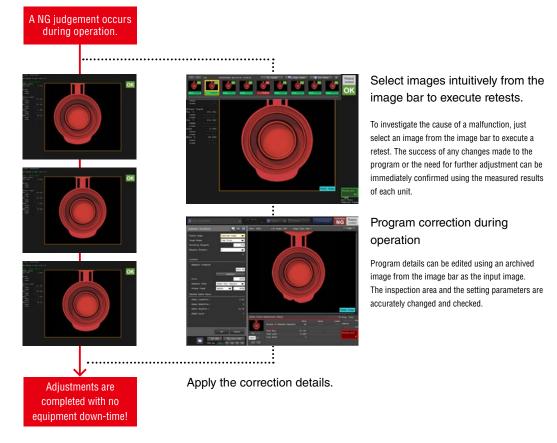
In addition, remote connection to controllers allows for real-time monitoring of a process or adjusting settings directly on vision controller firmware, avoiding the necessity of travelling on-site or experiencing a particularly harsh factory automation environment.



Even more stable configuration of settings

[Retest and edit programs with no interruption]

The XG-X Series supports nonstop retesting, which can be used to retest images and make adjustments without stopping the inspection processing, even while the line is in operation. While retesting archived images, it is possible to apply adjustments to the program after checking that the details are optimal. This makes it possible to confidently troubleshoot problems, while minimising down-time and eliminating repeated part inspections.



Quick changeover

[Background setting changes]

Program settings can be changed over in just 5 ms, the fastest in the industry. Simplified configuration for fast program settings, including support for inspection of multiple product types or multiple inspection across large parts.

Settings changeover in just 5 ms!

* Some restrictions apply when performing background settings changeover. Contact KEYENCE for details. Frequent inspection settings changeovers can affect the service life of the SD card. Please back up settings regularly.



Program 0001 inspection with side-attached components



Appearance inspection of metal processed surfaces after settings changeover to Program 0002 $\,$

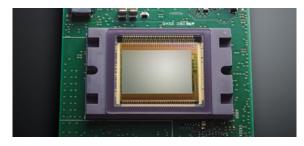
New Solutions Made Possible through 3D Image Processing

High-accuracy 3D inspection over the entire field of view



High resolution over large field of view

The 9.44 megapixel image sensor allows high resolution 2D and 3D images to be obtained over a wide field of view.



Telecentric lens with no positional deviation

The use of high-resolution telecentric lenses suppresses the effects of view angle resulting in accurate size observation as well as eliminating blind spots on the image.





ens

Four non-directional RGB projectors

Utilising pattern projection from four different directions enables imaging with no blind spots and with no directionality effects. The use of individual RGB illumination makes it possible to obtain highly accurate colour images similar to cameras with 3 image sensors (RGB).

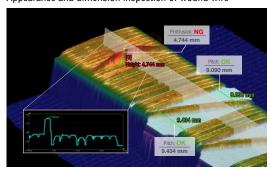


Applications

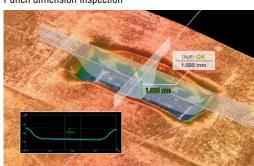
Simple extraction of unexpected 3D changes

■ In-line 3D appearance/dimension inspection of any target

Appearance and dimension inspection of wound wire

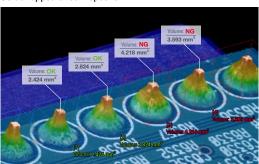


Punch dimension inspection

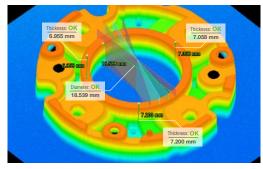


Inspection algorithm combining ease of use and accuracy

Solder appearance inspection



Resin-moulded product appearance inspection

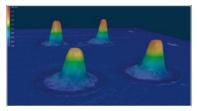


For in-line 3D inspection

XR Series

Image processing based on height information with 3D shape detection using bi-directional pattern projection lighting

Solder fillet inspection





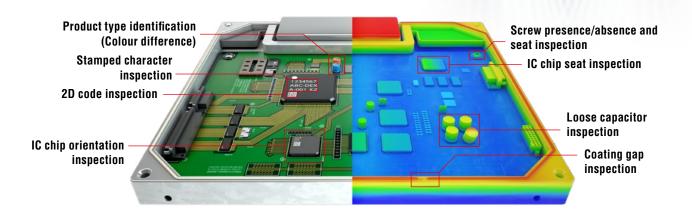
Pattern Projection Lighting

Simultaneous 2D + 3D inspection

Inspection with no blind spots with the use of eight-directional light transmission

The lighting incorporates Pattern Projection from eight light sources. This enables inspection without influence from target surface conditions or contrast by adding height data to conventional 2D inspection. The result is dramatically improved inline inspection stability.





3D inspection lighting

Pattern projection accurately captures target appearance

Multiple stripe patterns are projected at high speed. An ultra-highspeed CMOS sensor and processor analyse the light reflected from the targets in real-time to generate a 3D height image.



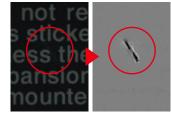
2D inspection lighting

LumiTrax[™] support for resolving problems with conventional imaging

Take advantage of numerous KEYENCE proprietary algorithms including LumiTrax™ Capture Mode, Auto-Teach Inspection, and Measurements and Dimensions Tools. This ensures stable inspection without influence from surface conditions or variations between good parts.

Dimension inspection

Appearance inspection

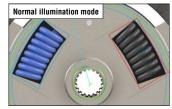


Solve inspection applications that incorporate height data alongside conventional image processing inspection



Clutch disc inspection

Capable of inspection for centre misalignment as well as spring colour difference checks with a colour camera. Also inspects for spring spillage in 3D difference checks.





Normal illumination mode

Product type difference checks using spring colours and assembly position inspection for centre components.

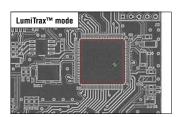
3D imaging mode

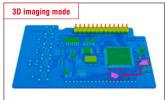
Inspects for spring spillage across multiple locations with 3D differentiation tools.



Appearance and foreign particle inspection on PCBs

Inspect for defects only, without influence from chip surface markings using LumiTrax™ mode. Inspect for fallen or foreign particles on PCBs with 3D detection tools.



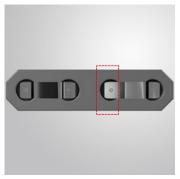


LumiTrax™ mode

Inspect for chip surface defects only, without influence from surface markings.

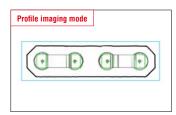
3D imaging mode

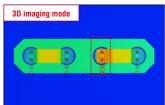
Capture variations in the overall PCB with 3D detection tools to inspect for the presence of fallen or foreign particles.



Lithium-ion battery terminal inspection

Captures profiles and inspects terminal positions. Captures terminal height data in 3D imaging modes to inspect for terminal weld disassembly.





Profile imaging mode

Profile capture stabilises searching by emphasising the appearance of terminals with low contrast.

3D imaging mode

Inspect for terminal height differences with battery cover standard positions using profile detection tools.

A fusion of 8-colour lights and an advanced algorithm

Completely New Colour Inspection Algorithm

Using a high-speed monochrome camera in combination with 8-wavelength lighting provides vastly superior capabilities compared with colour inspection with conventional colour cameras (RGB).

This allows users to achieve accurate sorting, even of the slightest differences in colour.

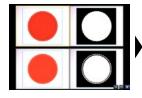
Colour

Accurate Sorting Even between Slight Colour Differences

Inspection of Various Types of Plastic Caps

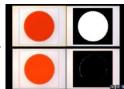


■ Conventional colour camera



Although some differences are noticeable, the extracted colours are largely the same.

■ Multi-spectrum mode



Differences in colour are clearly defined.



Detect Height Changes While Removing Glare

Stamped Character Inspection on Metal Casting

Problems with
Conventional Imaging





Difficult imaging conditions require trial and error for selecting the optimum light.

■ Conventional Cameras



The state of the surface makes extraction impossible.

I LumiTrax[™] MODE



Extraction of only shape (irregularity) information regardless of surface conditions

Multiple Product Types

The combination of multiple images and lighting colours enable the optimum lighting colour for each inspection item.

Multi-Capture Imaging (Lighting Colour Variation)



A red ink defect appears on a printing with a blue background.

■ 1st image capture: Red LED



Illumination using a red LED capable of clearly viewing the pattern is performed for position shift correction.

■ 2nd image capture: Blue LED



To erase the printed pattern for defect inspection, illumination using the same blue colour is performed.



Hardware and Software That Supports Inspection Stability

Built-In Dedicated Illumination Control Circuit

Ultra, High-Speed CMOS camera and Dedicated Control Circuit

Lighting Equipped with 8 High-Brightness LEDs of Different Wavelengths

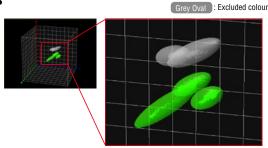
Photodiode and Real-Time Intensity Control Circuit -



Greater Inspection Stability

3D Display Function for Registered Colours

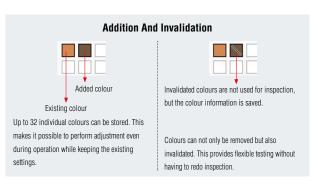
The distribution of registered colours can be displayed in 3D, indicating how different the registered selected and excluded colours are and allowing visualisation of whether the inspection is stable and free from interference from other colours.



Green Oval : Extracted colour

Multi-Colour Registration (Support for Invalidation and Integration)

Registration of up to 32 extracted colours and 32 excluded colours is possible. This makes it possible to handle a variety of inspection targets through added colour extraction without losing existing colour information. In addition, the ability to integrate or invalidate colours later allows for optimisation while always checking results.



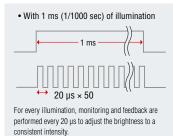
Real-Time Intensity Feedback Function

A built-in photodiode and real-time intensity control circuit provide LED emission level feedback control. Maintaining original brightness prevents deterioration in inspection capability due to LED degradation over time.

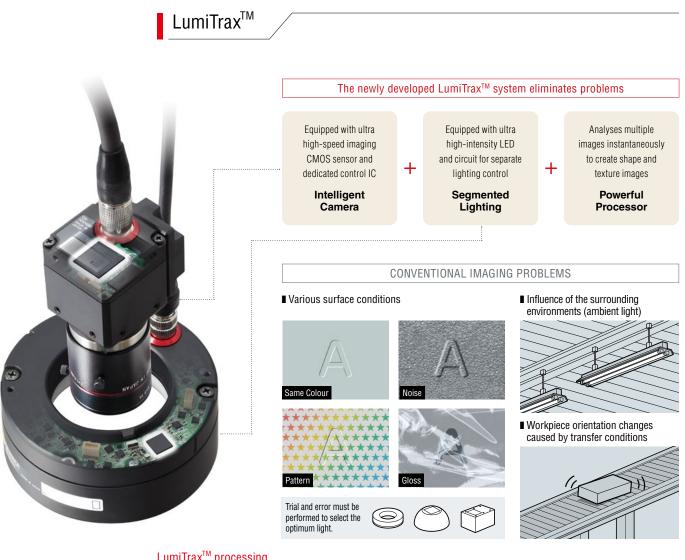


Photodiode and correction circuit within the lighting

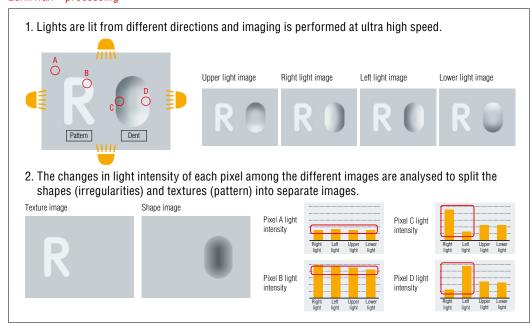
Illumination Time Chart



Integration of Camera, Lighting and Inspection Algorithm



LumiTrax[™] processing



Applications in various industries solved with LumiTrax[™]

Stamped character inspection



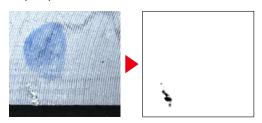
The stamped characters, which are bumpy, are inspected while ignoring the characters printed on the package.

Package opening perforation presence inspection



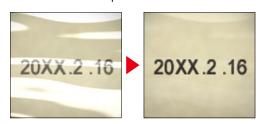
Even if a pattern is present in the background, inspection can be performed since it is possible to obtain the shape alone.

Chip inspection on a metal surface



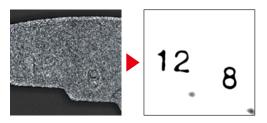
Factors such as remaining cleaning agent, dirt, and minor hairline fractures are cancelled so that only deep defects such as scratches and chips are detected.

Printed character inspection on a film surface



Glare, which affects inspections negatively, is eliminated to enable stable inspections.

Metal casting surface carved seal inspection



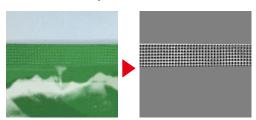
From a random casting surface, the carved seals with greater concave-convex information are emphasised.

Chip inspection on a printed surface



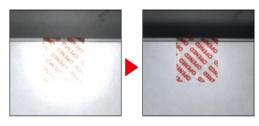
Images in which only the chips are extracted are created without being affected by the complex printed background.

Heat seal width inspection



The roughness information of sealed parts, for which changes are difficult to detect by means of colour or shading, are captured and extracted.

Tape presence inspection



Even when unexpected specular reflection occurs due to workpieces being tilted, the glare can be cancelled, which makes it possible to perform stable inspections.

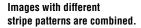
New imaging modes for detecting defects not possible with traditional line scan cameras

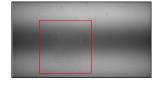
LumiTrax[™] Specular Reflection Mode

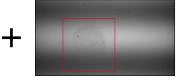
Various defects can occur due to a target's material or processing methods. With LumiTrax™ specular reflection mode, multiple images can be generated from a single image capture, allowing users to select the image data as required for the targeted defect.

Using the dedicated lighting allows for looped image capturing while the position of the emitted stripe pattern is changed in high-speed.









Create an image with only the defective area extracted.



Different calculation methods are used to create multiple images.

Main image types created through a single captured image









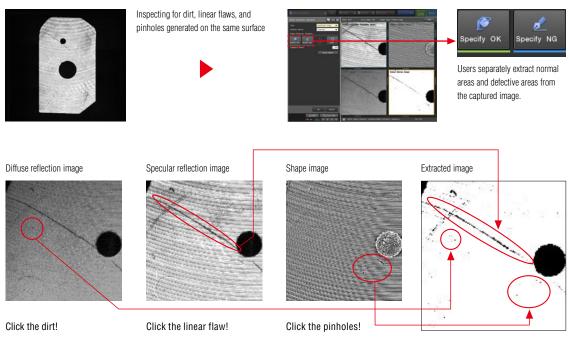


Normal image	Specular reflection image Diffuse reflection image G	Sloss ratio image Shape image			
Image type	Image creation method	Main applications			
Normal image	Averaging of all captured images	Determination of the overall image and as a basis for position correction			
Specular reflection image	Extraction of only specular reflection areas of the striped pattern	Inspection of glossy surfaces for linear flaws, rubbing flaws, etc.			
Diffuse reflection image	Extraction of diffuse reflections by comparing normal images and specular reflection images	Inspection of foreign particles and dirt			
Gloss ratio image	Extraction of variations in gloss by comparing specular reflection images and diffuse reflection images	Inspection of surface dullness and flaws on cylinders and other surfaces			
Shape image	Extraction of changes such as uneven surfaces through analysis of waviness that occurs in the striped pattern Inspection of dents, shallow unevenness, etc.				

Minute flaw detection algorithm for difficult inspections

Image calculation function (Defect extraction)

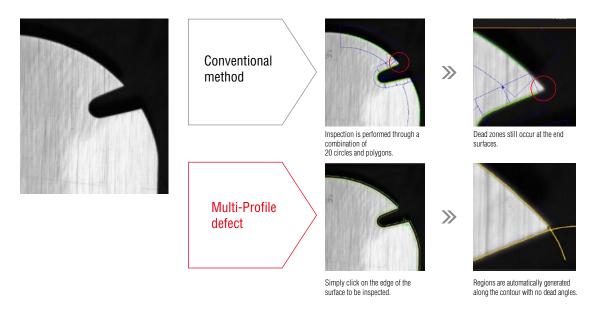
The LumiTrax™ specular reflection mode allows for easy separation of normal areas and defective areas simply by clicking on the multiple images generated. Because multiple imaging conditions are used, extraction according to the characteristics of the defect is possible.



Clicked defects are extracted.

Multi-Profile defect

Extraction of complex shapes is possible simply by clicking the contour area. Reference lines are generated even for rounded surfaces and acute corners. Any burrs or flaws detected beyond a reference line are considered defects.



Utilities that support stable image capturing

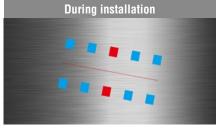
Line scan camera system with easy image creation for quick setup

Image creation with conventional systems is time-consuming. Not to mention, optical-axis alignment can be difficult. These built-in utilities solve these common problems with line scan cameras.

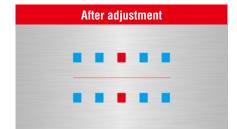
Line scan camera with built-in LED pointer

CA-HL02MX/HL04MX/HL08MX

An LED pointer is built in to each of these cameras. This allows the user to instantly determine the image capture area when installing the camera.







Users can instantly determine whether the optical axis has deviated from the target.

Line Scan Camera Settings Navigator

Using sensors incorporated in the camera and lights, Line Scan Camera Settings Navigator allows users to manage the position of each device digitally. This greatly reduces time spent on optical-axis alignment, a conventionally time-consuming task.

Line scan cameras





LED lighting







Quick image creation!

Simple 4-step Line Scan Camera Settings Navigator

STEP

Turn on the LED pointer and align the optical axis



To turn on a camera's LED pointer, simply check the box.

STEP 2

Adjust the angle of the line scan camera and the LED lighting



The positions of cameras and lights can both be checked using numerical values for the front, side, and top. Adjustment is even easier when using the dedicated jig.



STEP 3

Set the focus and brightness of the line scan camera



The focus and brightness are also represented numerically, allowing for value-based adjustment.

STEP 4

Set the X/Y ratio



Using a dedicated encoder enables automatic calculation of the optimal X/Y imaging ratio at the push of a button.



Dedicated encoder CA-EN100H

■ High-resolution, high-speed output

Support for up to 150000 pulses/revolution allows for high-resolution output at a minimum of 0.0024° (8.64 seconds). High-speed output is also possible at a maximum output frequency of 1.6 MHz

■ IP65-compatible

Added consideration for environmental resistance has resulted in a design that is even more resistant to water and dust, making devices easier to use in the worksite. (This does not include the head or shaft areas.)

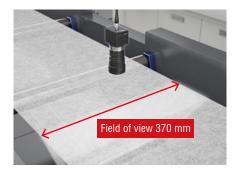
* If there is a chance that the shaft through-hole area will be exposed to oil droplets, use a cover or take other necessary precautions.

There is No Substitution for Resolution

Line scan camera

Obtain up to 67 megapixel images with a single camera





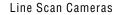
Large-capacity images with a valid pixel count of 67 megapixels (8192 \times 8192 pixels) are transmitted at 368 ms, 16 times faster than conventional models. Inspections requiring multiple area cameras can be performed with just 1 line scan camera and under uniform lighting conditions.

Entire target Detection of fine defects that are undetectable with area cameras is also possible.

Allows for stable detection with even lighting

Area Cameras

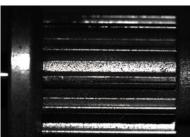
Area cameras cannot record optimum images due to the glare on the R part.



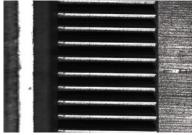
By recording images from an evenly lit part one line at a time, glare on the R part is eliminated.

0.5 mm defect (about 10 pixels)









Largest number of pixels in its class for high-resolution, wide-field inspection

64/21 megapixel cameras

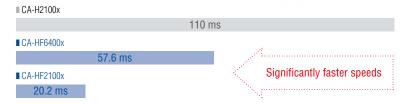
The 64 megapixel camera significantly improves accuracy in conventional inspections. The ability to capture a wider range with clear details using just a single camera helps ensure stable inspection. The increased transfer speeds also enable support for LumiTrax™ imaging.

More pixels and faster operating speeds

Transfer images up to 5.6 times faster (based on comparison with CA-H2100x) for improved inspection accuracy even with high-speed lines.

Image transfer time comparison (KEYENCE cameras)



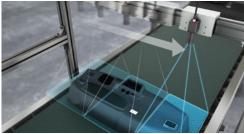


Applications

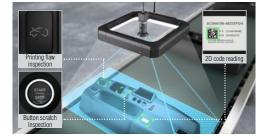
Wide field of view for shortened inspection time

When inspecting large targets, either the camera or the target must be moved to ensure accuracy, resulting in longer inspection times. With a high-resolution camera, however, the entire target can be imaged with a single capture, without sacrificing accuracy, and inspection can be performed with the shortest possible machine takt time. This also helps simplify equipment installation.

Automobile instrument panel inspection







High-resolution camer

Stable high-resolution, high-accuracy inspection

For inspections with multi-pin connectors, insufficient resolution can have a negative impact on inspection accuracy. High-resolution cameras ensure stable operation at the best possible resolution even for larger targets. This also eliminates the risk of camera calibration errors that are common with conventional multi-camera systems.

PCB connector inspection









High-resolution camera

Ultimate Defect Detection Tool

Defect Appearance inspection tool that offers superior detection stability

The defect tool detects flaws and other defects by checking for consistent intensity across a region. In addition to high detection ability, the tool also features a function that will filter the desired defects to detect, by size, intensity difference, shape, and count.



Original image



Binary image (Blob/Area Tool)



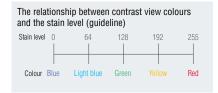
Defect inspection tool (stability screen)

■ Foreign particle detection on the inside of a container

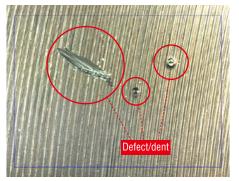
Conventional binary processing would not be able to detect the foreign particles as there is very little contrast between the particles and the dark portions of the container, however, defect inspection tool can compare the differences with the surroundings, allowing reliable detection of only the foreign particles.

Contrast view display

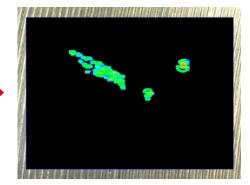
Using the colours blue, light blue, green, yellow and red, the contrast view display assigns a colour to defects according to the intensity difference between them and the surrounding area. The contrast view display updates in real time so you are able to see the defect position and intensity differences, allowing visual and intuitive confirmation of the differences between the defect you want to detect in comparison with the background or noise.



■ Defect detection for a metal plate



It is difficult to setup the defect tool parameters by values only on the standard camera image.

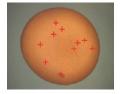


Using the contrast display, the intensity differences are clearly displayed in a colour coding so the parameters are easy to setup.

Grouping Filter Settings

After taking images of flaw detections as an entire group, it is possible to extract only images of the defects that you want. If only long, thin defects need to be detected, quality evaluation based on the appearance of the target can be performed. Various parameters can be set, such as area, circularity, main axis length, acicularity, length of the equivalent elliptical main shaft and countershaft ratio of the equivalent elliptical main shaft.

■Pill crack detection (before grouping filter setting)

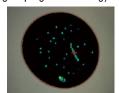


+ + + +

Reacts to ingredient particles and defects other than long thin cracks.

■Pill crack detection (after grouping filter setting)





Only long thin cracks are detected by using the area filter and the acicularity filter.

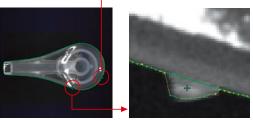
Profile defect

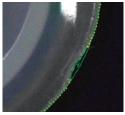
Edge defect inspection tool optimised for burr and flaw inspection

This tool extracts a profile from the edges of a workpiece and recognises the sections that show a large difference from the profile as burrs or flaws. In addition to circles and straight lines, ovals and profiles with complex shapes consisting of free curves are supported, based on edge information of up to 5000 points.

Burr/flaw detection for a plastic mould

Automatically generates a reference line of the profile of a workpiece including curves.



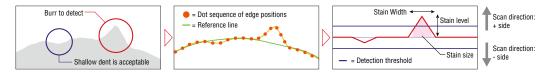


Detection of a burred section

Detection of a flawed section

Extensive Parameter Settings Support Various Defects

With a variety of parameters, you can distinguish defects you want to detect from the others. Settings can be optimised according to inspection category, such as +/- from the reference line (burrs/flaws) and width/size that exceeds a threshold.



Characterisation tool

[Characteristics features × Intensity information

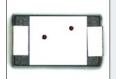
= Defect extraction to meet any needs]

The characterisation tool allows targets to be identified and classified based on greyscale rather than binary data. This enables true characterisation and filtering of detected targets based on true image data. Additional information for classifying and identifying defects that cannot be obtained through binarisation such as volume and level of change is also possible with this tool.

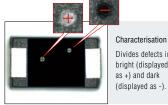
Differentiation of a variety of defects on a condenser

■ Light & dark defects Sorting bright and dark defects.





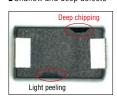




Divides defects into bright (displayed as +) and dark

■ Shallow and deep defects

Differentiating between deep chipping and light peeling.

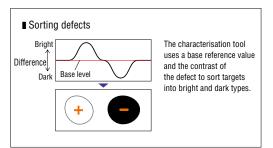


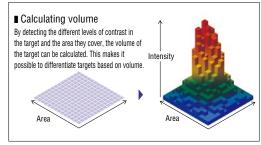


Blob (binary): Area With area there is no noticeable difference.



Characterisation: Volume measurement Differentiation is achieved by measuring the volume for each shade.





Fusion of Image Processing and Robotics



■Easy connection to robots

Programming for robots from various companies is available for creating a vision-guided robot system. This allows for seamless integration between the XG-X Series and robots.



Excellent compatibility that allows for use with any product

Simply selecting the manufacturer of the robot to use easily enables direct communication between the robot and the XG-X device. This allows for jog operations, auto-calibration, and other cooperation between the XG-X and the robot.

ABB	DAIHEN	DENSO
EPSON	FANUC	HIRATA
IAI	JANOME	KAWASAKI
KUKA	MITSUBISHI	NACHI
STAUBLI	SHIBAURA MACHINE	UNIVERSAL ROBOTS
YAMAHA	YASKAWA MOTOMAN	Custom

Automatic Calibration

Problems with conventional methods (manual method)

- ■Time-consuming manual configuration
- ■Accuracy varies between operators
- Readjustment is difficult if displacement occurs
- Reproduction at equipment delivery destinations takes time and effort



Benefits of KEYENCE's Vision-Guided Robots

- \blacksquare Easy, one-click operation
- Continuously high accuracy, no matter the user
- Immediate execution and restoration even with installation position deviations
- Quick, reliable reproducibility at any location



Proprietary Alignment System



■ High-resolution cameras

Highly accurate alignment over a wide field of view with 64/21 megapixel cameras

Easy configuration

Easy-to-navigate step-type settings menus

■ Flexible customizability

Customisable for wide range of alignment applications

High-accuracy alignment through easy operation

The XG-X Series boasts special functions for high-accuracy alignment.

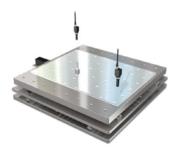
These functions make it easier to perform tasks that required extensive calculations with conventional models, resulting in an easy to use and configure interface.

Conventional processing is also available.

Twice as fast start-up

With conventional alignment devices, start-up involved a wide variety of preparation, including focus adjustment and calibration. The XG-X Series solves this problem by offering simple adjustment processes for each adjustment phase.

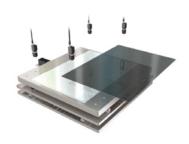
Compatibility with various system configurations



Two-camera centre alignment

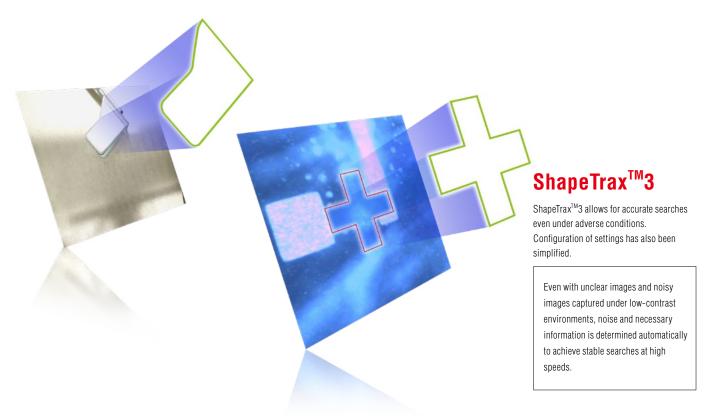


One-camera centre of gravity alignment



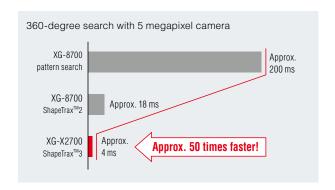
Four-camera side alignment

Perform Stress-Free, Fast, Applicable Searches



Significantly increased processing speed

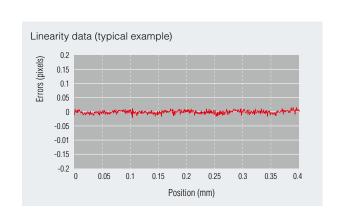
At a maximum of 50 times the conventional processing speed, a substantial increase in speed has been achieved by reexamining processing algorithms from the base level.



Ultra high accuracy

The linearity and repeatability are both 0.025 pixels, the highest level in the industry.

This tool satisfies demand for improved search accuracy by searching targets more finely and accurately.

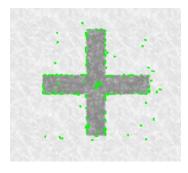


Newly developed automatic feature extraction algorithm

Whereas conventionally workers needed to be familiar with workpieces in order to extract contours, the XG-X automatically optimises settings, allowing menus and operation to be kept simple. Any worker is able to harness the full power of Shape $Trax^{TM}$ 3 for any workpiece.

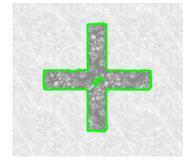
Conventional

With noisy markings, suitable contour extraction required an understanding of complex parameters.



$Shape Trax^{TM} 3$

Image noise is analysed automatically, making it possible to extract contours just as envisioned. Regardless of who configures the settings, searches that take full advantage of the device's performance can be performed.



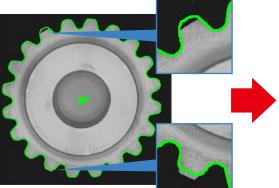
The industry's first "applied-skill" search

Rotation direction-added search

This new algorithm allows for both stabilised detection and faster speeds for circular, regular polygonal, and other shaped workpieces with partial features in the direction of rotation.

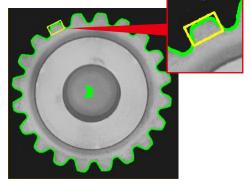
Conventional

Even when trying to accurately determine angles where teeth are short, the percentage of features for the entire workpiece is small, making stable inspection using only searching difficult.



Using rotation direction-added search

Once the position of the workpiece is detected, an additional search for features present in the direction of rotation is performed, allowing for stable, high-speed angle determination even for only slight features.



Detection target selection conditions

When performing robot picking and the like, analysis of the profile feature for slight differences is performed at the same time as space determination for gripping the workpiece. This eliminates the need for complex branch condition settings and calculations, anyone is able to use the device to its fullest potential easily.



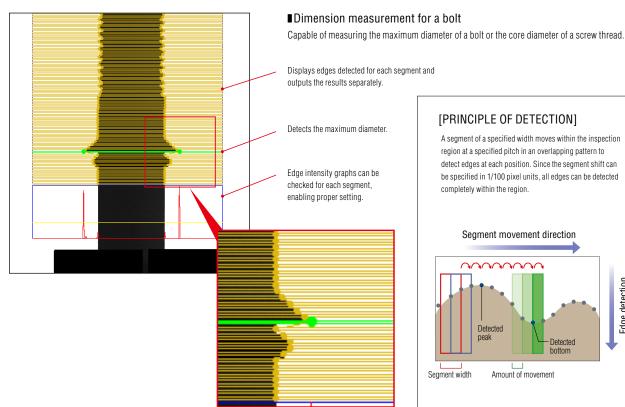
Simply by adding regions at both ends of the workpiece to the target selection conditions, determining whether there is enough space for the gripper to enter can be performed at the same time as the search.

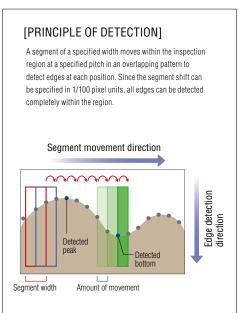
Measure Up to 5000 Points within One Region

Trend edge

Instant profile measurement for an entire area

This tool detects up to 5000 edges within the inspection region and outputs their positions and widths. In addition to all edge data, maximum/ minimum/average widths, tip position, and peak-to peak width can be measured without complicated calculations. It is also possible to find a virtual circle or approximate line from the information of the detected multiple points.

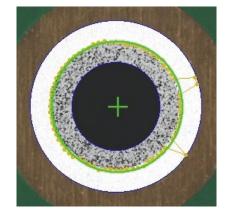




■Circular/Arc processing

Detecting PCB hole centres

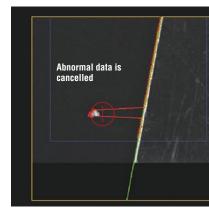
Trend edge can calculate the centre position and diameter of a circle by detecting multiple edge points around a curve, using this data to project a best fit circle. Abnormal edge positions can be filtered and ignored before drawing the virtual circle to allow for reliable measurements



■Linear processing (Abnormal point removal)

Detecting the position of glass substrate edges

The trend edge tool can map a virtual straight line from all of the edge positions along a substrates edge. With the ability to filter and ignore abnormal points the virtual straight line can be used for accurate position, angle, reference and geometric data.



Capable of Handling All Inspection Needs

OCR2

Simple and Reliable Character Recognition Tool

A tool that checks printed and engraved characters on products.

Simply select the area for inspection and with a press of a button, the image processing settings will automatically be tuned for the best results. Any user can set the tool up.



■ Customisable user dictionary



Built-in library can be used in combination with user-defined characters.

thracters. Achieves stable ID and OCR/OCV through sub-pattern registration, even with variable print quality. The number of readable characters has also increased to 40, including the "+" symbol.

■ Highly robust



Achieves robust performance thanks to a newly developed algorithm, even with background noise or low contrast.

Makes stable inspections possible.

1D/2D code reading

Executes reading and image processing inspection simultaneously

Various inspections, such as inspections of the external appearance and dimensions, can be performed simultaneously with the reading of 1D and 2D codes printed on the target or with the inspection of the quality of the printed 1D and 2D codes. By removing the need for both conventional 1D & 2D code readers and a camera for image processing, space and money can be saved with the use of this tool.

■ Capable of handling various types of codes



Simultaneous reading of barcodes and characters



Composite Code

2D CODES







at the same time.

Supported standards 1D: ISO/IEC 15416

■ Print quality verification function

2D: ISO/IEC 15415, AIM DPM-1-2006, SAE AS9132

This newly added function to verify 1D/2D code printing quality enables inline checking of relative changes in printing quality while performing reading

OK Detects defects in 1D code printing to judge the code as NG.



Notice:

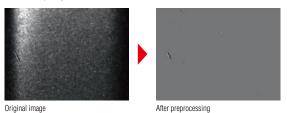
This function is designed to capture relative changes in print quality and thus cannot be used as a print quality verification system for absolute value evaluation.

Highlight and Improve Features That Previously Could Not Be Seen. Remove Features and Aspects of an Image for Stable Inspection.

Shading correction (real time)

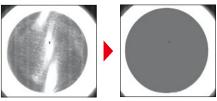
Shading correction is a real time filter that evens out any large random shadows or glare on a target surface, leaving behind smaller defined points which are often associated to being flaws or defects. As this is a grey scale processing filter, it dynamically changes the processed image based on the input image rather than being based on a fixed binary setting level. This ensures consistency with target variation and changes in

■ Surface quality on a metal roller



Shading correction can be used to extract just bright, dark or both bright and dark defects depending on the nature of the surface.

■ Defect detection on the bottom of a can



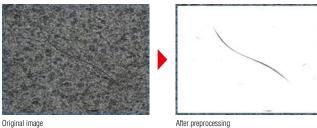
After preprocessing

Cancelling out the hot-spots caused by changes in the target surface creates a uniform background that makes it possible to detect defects

Scratch defect extraction

Eliminates noise information within the inspection region and only highlights linear information. This filter is particularly effective for linear defect inspection for workpieces having rough surface conditions.

■ Linear defect on a metal component

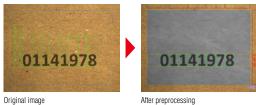


Only linear defects are extracted by ignoring background noise.

Noise isolation

Eliminates or, in contrast, extracts noise having a specified area or smaller. This filter is effective when a rough background hinders image processing or to detect subtle defects.

■ Recognition of characters printed on cardboard



Original image

Only bright and dark noise are removed and the printing condition remains unaffected

■ Defect inspection for a plastic mould



Only black defects smaller than the specified area are extracted

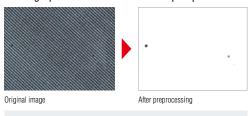
KEYENCE's Proprietary Algorithms for an Optimal and Stable Inspection

Bidirectional smoothing

Has an effect that removes a significant amount of fine background patterns or noise.

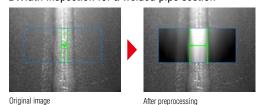
This filter can be set to have an effect that performs smoothing in individual directions (X/Y), thus making it applicable for a wide range of applications, including counting individual items.

■Foreign particle detection on a striped pattern



By eliminating the striped texture to the target, foreign particles can be

■Width inspection for a welded pipe section

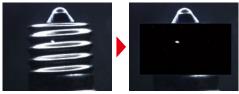


The blur filter allows a stable width measurement by eliminating unnecessary featured points other than the welded section.

Individual filter processing direction

As for the blur filter, all directions can now be applied for "shading correction", "image extraction", "expand, and "shrink" filters. Being able to choose the processing direction helps to enhance the image according to how the feature appears.

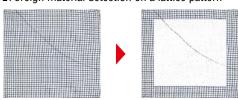
■Individual filter processing direction



[Filter used: Shading correction] Processing direction: X

The defective area is isolated by removing the directional shading on the thread.

■Foreign material detection on a lattice pattern

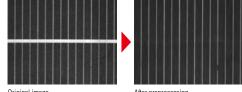


Original image

[Filter used: Image extraction] Processing direction: X -> Processing direction: Y

The background lattice pattern is removed by applying the filter multiple times while changing the processing direction.

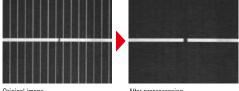
■Inspection of grid lines on a solar cell



[Filter used: Shrink] Processing direction: Y

The break is enhanced while the width of the grid lines remain and the bus bar is removed for stable inspection.

■Inspection of bus bars on a solar cell



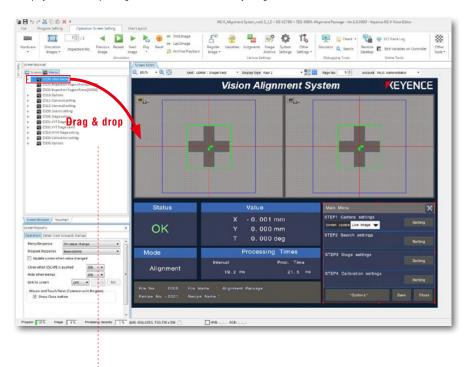
[Filter used: Shrink] Processing direction: X

The grid lines on the background are removed by shrinking the image in the X direction broadening the break in the bus bar.

Fully Customisable Operator Screens & Menus

Screen Editor

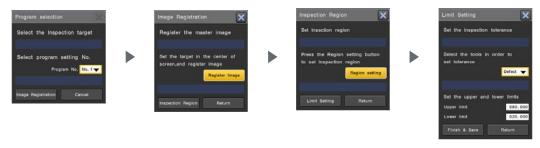
Controller display screens and operating interfaces can be created easily using the Screen Editor.



Drag & drop items from the list to the screen for simple GUI building.

Custom menu creation

Step by step procedures for changes such as product change over or shift adjustments can be simplified with customised operator menus.



By creating menus for a step by step process (such as calibration) there are no reasons why adjustments shouldn't be made or settings being incomplete and steps missed.

Conventional Systems

Due to different adjustment methods and different personnel making changes, cases often emerge where the setting is incorrect or varies between operators. With conventional systems complex parameter driven menus may need to be understood. It takes time and resources for operators to be trained and sometimes due to the complex menu interface the ability to operate the machine is limited to a few people.

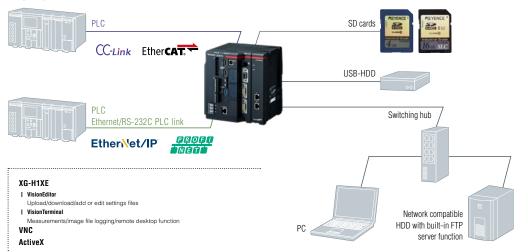


Custom dialogue

Necessary steps and required settings can be put together to match up with the process. Menus can also be attributed to the relevant aspects of the image processing flowchart. This helps make sure that any operator of any level can easily be guided through the process required on the machine.

Save image and data for analysis and simulation

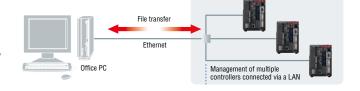
Supports a variety of connections between PLCs from various manufacturers and exchanges results and commands via the data memory just by selecting the connection destination manufacturer/device. As standard, the main unit is equipped with I/O, RS-232C, Ethernet, USB, and SD card slots. Furthermore, it is also possible to check communication with the communication monitor. This achieves significant reductions in cost, time, and effort.



 $\label{eq:charge_energy} \textbf{EtherCAT}^{\$} \ \text{is registered trademark and patented technology, licensed by Beckhoff Automation GmbH, Germany.}$

Remote data logging & monitoring software XG-X VisionTerminal

The XG-X VisionTerminal software enables the remote monitoring, logging and support of any XG-X Series controller connected to a PC via a standard network. Maintenance man-hours, down-time and business trips can be significantly reduced as problems can be resolved remotely with the transfer of setting files and image data.



Main functions

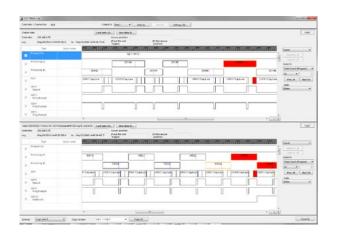
Remote desktop function ... Enables the verification and remote operation of a connected controller, without extra data being sent and interfering with controller processing.

.ogging function Enables the display, logging of measurement results and storage of image data to a PC folder from an inspection with any connected controller. This function also supports the accumulation output buffer of the controller to ensure complete data collection.

File acquisition function ... Enables the transferring of setting data files and image data files between the XG-X Series controller and a PC

Trace log function

The trace log function is a great tool to help with processing and I/O troubleshooting. Giving integrators and developers the capability for checking and monitoring the sequencing of units being processed, I/O signals and commands. The results display can be split and the processing time for each unit along with other information can be easily displayed. The trace log can also be saved and be used at a later date as a reference guide.



■Camera lineup

		Model	Specification	Function	Capture range (pixels)	Image transfer time
64 megapixel camera series		CA-HF6400M CA-HF6400C	90× high-speed monochrome 88× high-speed colour	High speed	8192 × 7808	57.6 ms 59.2 ms
21 megapixel camera series		CA-HF2100M CA-HF2100C	85× high-speed monochrome 85× high-speed colour	High speed	5104 × 4092	20.2 ms
5 megapixel camera series	The state of the s	CA-H500MX CA-H500CX	16× high-speed monochrome 16× high-speed colour	High speed, high performance*1	2432 × 2040	27.7 ms 29.2 ms
		CA-H500M CA-H500C	16× high-speed monochrome 16× high-speed colour	High speed, environment resistant*2	2432 × 2050	28.4 ms
2 megapixel camera series	Time	CA-H200MX CA-H200CX	16× high-speed monochrome 16× high-speed colour	High speed, high performance*1	1600 × 1200	11.7 ms
		CA-H200M CA-H200C	16× high-speed monochrome 16× high-speed colour	High speed, environment resistant*2	1600 × 1200	11.8 ms
		CA-200M CA-200C	Monochrome Colour	Environment resistant*2	1600 × 1200	56.5 ms
	160	CA-HS200M CA-HS200C	16× high-speed compact monochrome 16× high-speed compact colour	High speed, compact	1600 × 1200	14.2 ms
0.47 megapixel camera series	CA-H048MX	16× high-speed monochrome	High speed,	784 × 596	2.9 ms	
		CA-H048CX	16× high-speed colour	high performance*1	512 × 480	1.7 ms
0.31 megapixel camera series	100	CA-H035M CA-H035C	16× high-speed monochrome 16× high-speed colour	High speed, environment resistant*2	640 × 480	2.9 ms
		CA-035M CA-035C	Monochrome Colour	Environment resistant*2	640 × 480	16.5 ms
	•	CA-HS035M CA-HS035C	7× high-speed compact monochrome 7× high-speed compact colour	High speed, compact	640 × 480	4.5 ms

^{*1} Colour cameras support LumiTrax ** image capture and pattern projection lighting, and monochrome cameras support LumiTrax ** image capture, pattern projection lighting, and LumiTrax ** specular reflection mode image capture. *2 To use this camera as an IP64-rated, environment-resistant camera, use it with a KEYENCE-specified IP64-rated lens and an environment-resistant cable.

		Model	Applicable lens	Number of pixels	Max. expanded image size	Scan speed	Pixel clock
Line scan camera series		CA-HL02MX	1 in. C-mount	2048	2048 × 16384	6.1 µs/line	165 kHz
		CA-HL04MX	1 in. C-mount	4096	4096 × 16384	10.2 μs/line	97.7 kHz
	LumiTrax™ specular reflection mode	CA-HL08MX	2 in. special mount (M40 P0.75) lens*1	8192	8192 × 8192	10.2 µs/line	97.7 kHz

^{*1} F-mount lenses supported with an F-mount conversion adapter.

3D cameras

		Model	Field of view XY (Reference distance)	Z range (from reference distance)	Repeatability (σ)
VT		XT-024	24 × 24 mm	±2 mm	±0.5 μm
ХТ		XT-060	60 × 60 mm	±6 mm	±1 μm
XR	Tenng T	XR-HT15M	12.5 × 12.5 mm	±1.5 mm	1 μm* ¹
AN		XR-HT40M	35.5 × 35.5 mm	±5.0 mm	2 μm*¹

 $^{^{\}star}1\ \ Value\ for\ KEYENCE\ standard\ plane\ workpieces\ when\ binning\ is\ ON\ and\ a\ 3\times 3\ average\ filter\ is\ used\ once.$

■ Controller lineup

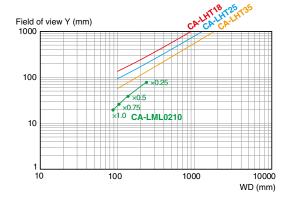
The XG-X Series offers the same ease of use for all applications without having to select between a stand-alone type for simple applications and a PC-based type for more difficult applications. With a wide selection of devices that allows for selection of the best controller to fit the situation—including the application, required processing speed and capacity, and connected

			Area c			camera-only models				Models compatible with high-resolution cameras	
				# 5 P						Ē	
Model			XG-X1000	XG-X1200	XG-X1500	XG-X2000	XG-X2200	XG-X2500	XG-X2700	XG-X2800	XG-X2900
	, total number of c calculation DSP c			7 (2)		8	(high-speed DSP:	3)	14	(high-speed DSP	7)
	0.31 to 0.47 megapixels	CA-(H)035x CA-HS035x CA-H048xX	√ *¹	√* ¹	√ *1	~	✓	✓	~	·	√
	2 megapixels	CA-(H)200x CA-HS200x CA-H200xX	_	√ *1	√ *1	_	~	√	~	~	√
	5 megapixels	CA-H500x CA-H500xX	_	_	√ ∗¹	_	_	√	✓	✓	~
Supported	21 megapixels	CA-HF2100x	_	_	_	_	_	_	_	√ *5	~
cameras	64 megapixels	CA-HF6400x	_	_	_	_	_	_	_	_	√
	Line scan camera	CA-HL02MX CA-HL04MX CA-HL08MX	_	_	_	_	_		_	✓*2*3	√ *²
	XR	XR-HT15M XR-HT40M	_	_	_	_	_	_	_	√ *²	√ *²
	XT	XT-024 XT-060	_	_	_	_	_	_	_	√ *²	✓*²
Built-in can	nera interface		2	2	2	2	2	2	2	*4	* ⁴
Dedicated t	ouch panel (RS-23	32C)	✓	✓	~	~	✓	✓	✓	✓	✓

^{*1} Image capture modes other than normal illumination mode are not supported.
*2 When connected to an XT or XR camera, do not use with the 3D capture mode of an area camera or with a line scan camera.
*3 LumiTrax** Specular reflection mode is not supported.
*4 Use in combination with a separate camera input unit.
*5 LumiTrax** image capture is not supported.

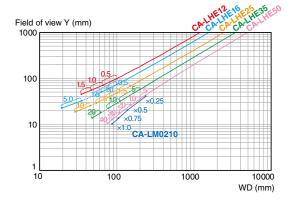
■CA-HF6400C/CA-HF6400M

(When the CA-LHT Series is attached)



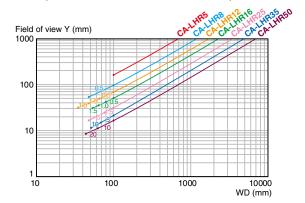
■CA-HF2100C/CA-HF2100M

(When the CA-LHE Series is attached)



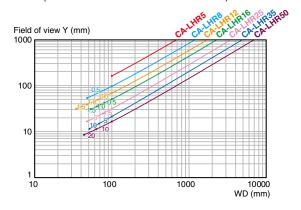
■CA-H500CX/CA-H500MX

(When the CA-LHR Series is attached)



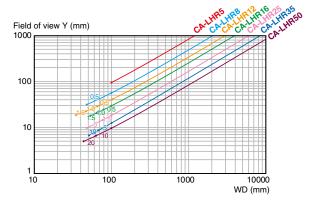
■CA-H500C/CA-H500M

(When the CA-LHR Series is attached)



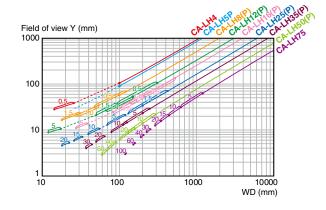
■CA-H200CX/CA-H200MX

(When the CA-LHR Series is attached)



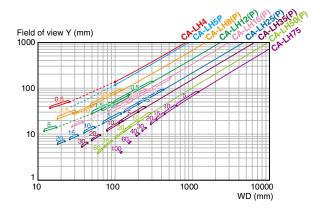
■CA-H200CX/CA-H200MX

(When the CA-LH/LHxP Series is attached)



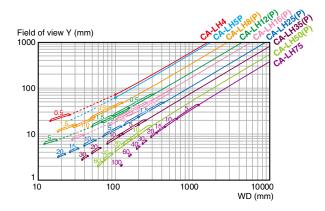
■CA-200C/CA-200M/CA-H200C/CA-H200M

(When the CA-LH/LHxP Series is attached)



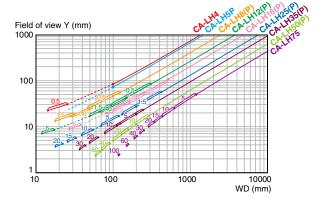
■CA-H048CX/CA-H048MX

(When the CA-LH/LHxP Series is attached)



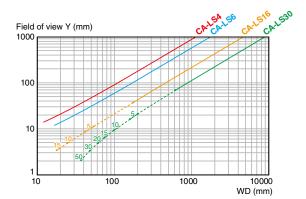
■CA-035C/CA-035M/CA-H035C/CA-H035M

(When the CA-LH/LHxP Series is attached)



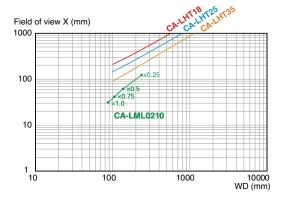
■CA-HS035C/CA-HS035M

(When the CA-LS Series is attached)



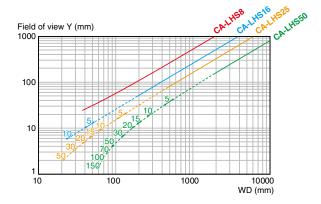
■CA-HL08MX

(When the CA-LHT Series is attached)



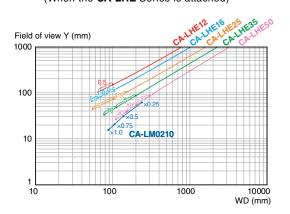
■CA-HS200C/CA-HS200M

(When the CA-LHS Series is attached)

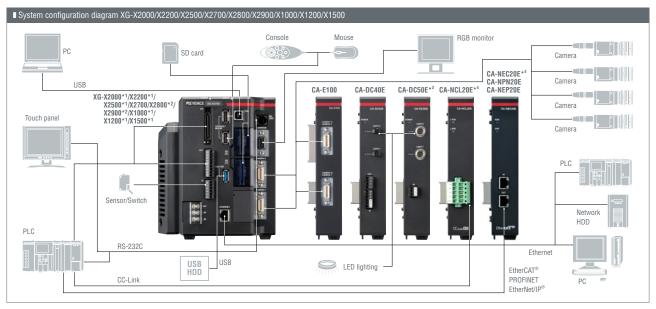


■CA-HL02MX/CA-HL04MX

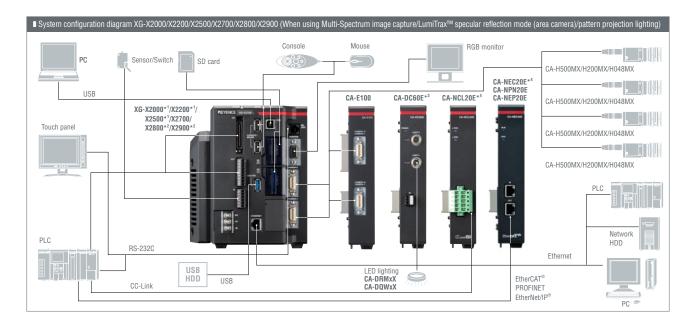
(When the CA-LHE Series is attached)

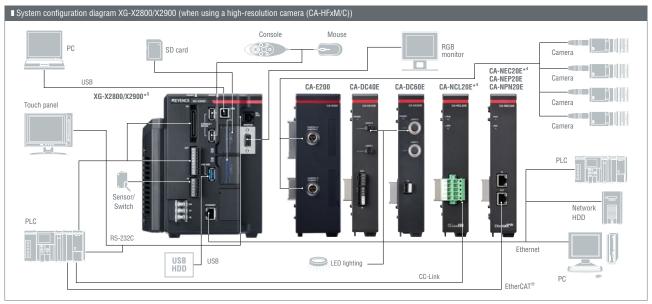


^{*} Using close up rings may result in distortion and lower resolution around the edges of the image area/image sensor. For other field of view graphs, refer to the user's manual.

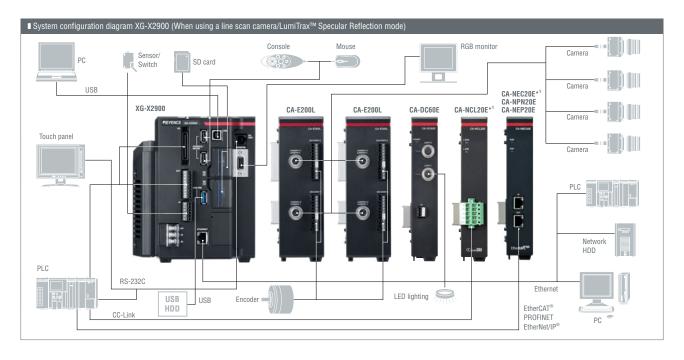


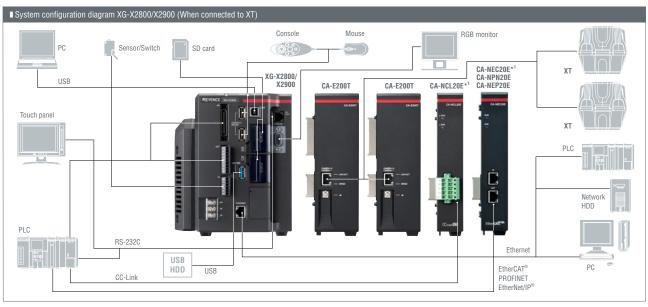
- *1 Fan units cannot be connected to XG-X2000/X2200/X2500/X1000/X1200/X1500. *2 XG-X2800/X2900 has no camera connection ports, must use with at least one camera input unit.
 *3 LumiTrax™ mode is unavailable when used with the XG-X1000 Series. CA-DRWxX lights can be used as standard high-intensity lighting *4 The CA-NCL20E and the CA-NEC20E cannot be connected at the same time.

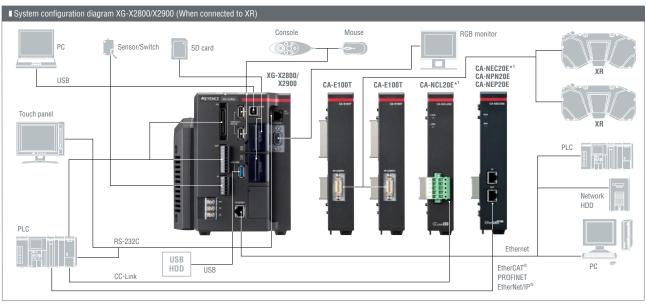




^{*1} Fan units cannot be connected to XG-X2000/X2200/X2500. *2 XG-X2800/X2900 has no camera connection ports, must use with at least one camera input unit.
*3 LumiTrax™-Specular Reflection mode can only be used on the XG-X2900 controller. *4 The CA-NCL20E and the CA-NEC20E cannot be connected at the same time.
*5 The CA-HF6400x and LumiTrax™ imaging with the CA-HF2100x can only be used with the XG-X2900.







^{*1} Only one communication expansion unit (CA-NCL20E/NEC20E/NEP20E/NPN20E) can be connected.

■ Controller



5 megapixel camera-compatible XG-X2700/XG-X2500/XG-X1500

camera-compatible XG-X2200/XG-X1200

0.47 megapixel camera-compatible XG-X2000/XG-X1000



Line scan camera/ XT/XR/21/64 megapixel camera-compatible XG-X2800/XG-X2900

■ Expansion unit



Area camera input unit CA-E100



High-resolution area camera input unit CA-E200

Dedicated to the XG-X2000 Series



Line scan camera input unit CA-E100L

Dedicated to the XG-X2000 Series



XR camera input unit CA-E100T

Dedicated to the XG-X2000 Series



XT camera input unit CA-E200T

Dedicated to the XG-X2000 Series



High-speed transmission line scan camera input unit CA-E200L

Dedicated to the XG-X2000 Series



LED light control expansion unit CA-DC40E



LumiTrax[™]-compatible light control expansion unit



Multi-Spectrum/pattern projection/ LumiTrax™ specular reflection mode-compatible light control expansion unit

CA-DC60E

Dedicated to the XG-X2000 Series



CC-Link unit CA-NCL20E



EtherCAT® unit CA-NEC20E



PROFINET module CA-NPN20E



EtherNet/IP® module CA-NEP20E

^{*1} LumiTrax™ mode is unavailable when used with the XG-X1000 Series. CA-DRWxX lights can be used as standard high-intensity lighting.

■ Area Cameras



88x speed colour / 90x speed monochrome 64 megapixel camera CA-HF6400C (Colour) CA-HF6400M (Monochrome)



85x speed, LumiTrax™-compatible 21 megapixel camera CA-HF2100C (Colour) CA-HF2100M (Monochrome)



16x speed, environment-resistant 5 megapixel camera CA-H500C (Colour) CA-H500M (Monochrome)



Environment-resistant 2 megapixel camera CA-200C (Colour) CA-200M (Monochrome)

16× speed, environment-resistant 0.31 megapixel camera CA-H035C (Colour) CA-H035M (Monochrome)

Environment-resistant 0.31 megapixel camera CA-035C (Colour) CA-035M (Monochrome)



Ultra-compact (16x) 2 megapixel camera CA-HS200C (Colour) CA-HS200M (Monochrome)



Ultra-compact (7×)
0.31 megapixel camera
CA-HS035C (Colour)
CA-HS035M (Monochrome)



16x speed, high-performance 5 megapixel camera CA-H500CX (Colour) CA-H500MX (Monochrome)

16x speed, high-performance 2 megapixel camera CA-H200CX (Colour) CA-H200MX (Monochrome)



16x speed, high-performance 0.47 megapixel camera CA-H048CX (Colour) CA-H048MX (Monochrome)

■ Line Scan Cameras



8192 pixels High-speed Line scan camera **CA-HL08MX** (Monochrome)



4096 pixels High-speed Line scan camera **CA-HL04MX** (Monochrome)



2048 pixels High-speed Line scan camera **CA-HL02MX** (Monochrome)

■ XT/XR



24 mm type
XG-X controller model
XT-024



60 mm type
XG-X controller model
XT-060



40 mm type
XG-X controller model
XR-HT40M
GigE model
XR-HT40MD



15 mm type
XG-X controller model
XR-HT15M
GigE model
XR-HT15MD

■ Programmable Encoder



Encoder head unit CA-EN100H



Encoder relay unit CA-EN100U



CA-EN5 (5 m) CA-EN10 (10 m)

■ Accessories

Camera cables



Models

Cable type	Connector	Camera cable length				Extension cable	Repeater cable
Cable type	shape	3 m	5 m	10 m	17 m	5 m, 10 m	3 m, 5 m, 10 m
Standard	Straight	СА-СН3	CA-CH5	CA-CH10	_	_	CA-CH3X (3 m) CA-CH10X (10 m)
	L-shaped	CA-CH3L	CA-CH5L	CA-CH10L	_	_	_
High-flex, environment-resistant	Straight	_	CA-CH5BP	CA-CH10BP	_	CA-CH5BPE (5 m)	_
High-flex	Straight	CA-CH3R	CA-CH5R	CA-CH10R	CA-CH17R*1	_	CA-CH3BX (3 m) CA-CH5BX (5 m) CA-CH10BX (10 m)
For high-speed transmission cameras	Straight	CA-CF3	CA-CF5	CA-CF10	_	CA-CF5E (5 m) CA-CF10E (10 m)	_
tranomiosion cameras	L-shaped	CA-CF3L	CA-CF5L	CA-CF10L	_	_	_

^{*1} The max. cable length varies depending on the use of extension cables/amplifiers. Contact KEYENCE for details.

Camera cable compatibility

			Area cameras			Line scan cameras
Cable type	CA-HF6400x/HF2100x	CA-H500x/H200x/H035x	CA-H500xX/H200xX/ H048xX	CA-200x/035x	CA-HS200x/HS035x	CA-HL×MX
CA-CH3 (L/R)	_	✓	✓	✓	✓	_
CA-CH5 (L/R/BP)	_	✓	✓	✓	✓	_
CA-CH10 (L/R/BP)	_	✓	✓	✓	✓	_
CA-CH17R	_	_	_	*1	_	_
CA-CF3 (L)	✓	-	_	_	-	✓
CA-CF5 (L)	✓	_	_	_	_	✓
CA-CF10 (L)	✓	_	_	_	_	✓

^{*1} The CA-CH17R cable can only be used for connecting the CA-035x camera.

Amplifier for extension cables CA-CHX10U



Camera cables can be extended up to 37 m*.

* The maximum length varies depending on the camera model. Contact us for details.



The dedicated extension cable is necessary in order to connect an amplifier to a camera or between two amplifiers. Contact KEYENCE for details.

XT camera cable **CA-CD2** (2 m) **CA-CD5** (5 m) **CA-CD10** (10 m)



XT power supply cable **OP-88356** (2 m) **OP-88357** (5 m) **OP-88358** (10 m)



■ Monitor/Touch panel



Multi-touch enabled 12" touch panel CA-MP120T 12" colour LCD monitor CA-MP120

8.4" colour LCD monitor CA-MP82

CA-MP120T/MP120 monitor stand OP-87262



CA-MP120T protective film OP-87263

Options for CA-MP120T For XG-X Series:

OP-87264

(Touch panel modular RS-232C cable, 3 m)

OP-87265

(Touch panel modular RS-232C cable, 10 m)



CA-MP120T/MP120 pole-mounting bracket OP-42279



Monitor cable **OP-66842** (3 m) **OP-87055** (10 m)

* A RGB monitor cable and touch panel RS-232C cable are required when using the CA-MP120T.

■ Communication cable

Parallel I/O cable **OP-51657** (3 m) Communication cable conversion connector

OP-26486: 9 pins For 9-pin SYSMAC: **OP-84384** For 9-pin MELSEC: OP-86930

* When connecting the MELSEC-FX3/FX5, which requires a 9-pin connection, use the OP-26486.



RS-232C communication cable **OP-26487** (2.5 m)



1 Gbps Ethernet cable **OP-66843** (3 m)



USB cable **OP-66844** (2 m)



PC connection cable for XR **CA-CD2** (2 m) **CA-CD5** (5 m) **CA-CD10** (10 m)



XR power supply cable **CA-CP2** (2 m) **CA-CP5** (5 m) **CA-CP10** (10 m)

■ Others



Image processing system integration software XĞ-H1XE See the chart below for information on supported operating systems.



XG-X Series USB handheld controller OP-87983



Dedicated mouse OP-87506 Mouse stand OP-87601



Industrial SD card **CA-SD16G**: 16 GB CA-SD4G: 4 GB CA-SD1G: 1 GB **OP-87133**: 512 MB



Dedicated 24 VDC power supply CA-U4 CA-U5

The XG-X Series manual set OP-M**** is not included with the controller.

A PDF version is included with the integrated development environment software XG-H1XE.



XR camera air purge unit XR-AP1

Air purge function keeps the sensor head clean. Air purge units are recommended for sideways or upward sensor installations

Calibration target For XT-024: **OP-88400** For XT-060: **OP-88401**

For XR-HT15M(D): **OP-87740** For XR-HT40M(D): OP-87741

By using the calibration target for the XR/XT Series, accuracy can be maintained even if temporal changes in measurements occur.

Height difference gauge OP-87742

As a tool for checking accuracy, this reference gauge provides readings traceable to international standards.

Dedicated stand for XT OP-88427

Supported OS and recommended running environment for XG-H1XE

Supported OS	Microsoft Windows 10 Home, Pro, Enterprise (64 bit version) Cannot be used with an OS that is not listed above.
Running environment	CPU: Intel® Core™ i3 processor equivalent or higher RAM: 8 GB or more HDD: 8 GB or more (with additional space for storing images required) Besides these, if installation of Microsoft .NET Framework is necessary, 4.5 GB or more of free space is required in addition to the above. Monitor: 1024 × 768 pixels or more (1280 × 1024 pixels or more recommended). An internet connection for accessing the webpage for submitting the activation code request and a means of receiving activation code via e-mail is required.

^{*} Microsoft is either registered trademarks or trademarks of Microsoft Corporation in the United States and/or other countries. Intel and Intel Core are registered trademarks of Intel Corporation in the United States and other countries

Controller (XG-X2700/XG-X2500/XG-X2200/XG-X2000)

Model	`	XG-X2700	XG-X2500	XG-X2200	XG-X2000
Camera inp	out		ochrome cameras, up to 4 inputs can be connected		,
	Trigger input		ture with up to 4 cameras can be selected (up to 2		
Supported cameras/ Number of pixels		CA-035C/HS035C/H035C/035M/HS035M/H035M 0.31 megapixel mode: 640 (H) × 480 (V), approx. 0.31 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels CA-H048CX/H048MX 0.47 megapixel mode: 784 (H) × 596 (V), approx. 0.47 megapixels 0.31 megapixel mode: 640 (H) × 480 (V), approx. 0.47 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels CA-200C/HS200C/H200C/200M/HS200M/H200M 2 megapixel mode: 1600 (H) × 1200 (V), approx. 1.92 megapixels 1 megapixel mode: 1024 (H) × 960 (V), approx. 0.98 megapixels CA-H200CX/H200MX 2 megapixel mode: 1600 (H) × 1200 (V), approx. 1.92 megapixels CA-H500C/H500M 5 megapixel mode: 2432 (H) × 2050 (V), approx. 4.99 megapixels CA-H500CX/H500MX 5 megapixel mode: 2432 (H) × 2050 (V), approx. 4.96 megapixels 2432 (H) × 2040 (V), approx. 4.96 megapixels 2 megapixel mode: 2432 (H) × 2040 (V), approx. 4.96 megapixels 2 megapixel mode:		n200W 2 megapixel mode: 1600 (H) x 1200 (V), approx. 1.92 megapixels 1 megapixel mode: 1024 (H) x 960 (V), approx. 0.98 megapixels • CA-H200CX/H200MX 2 megapixel mode: 1600 (H) x 1200 (V), approx. 1.92 megapixels	CA-035C/HS035C/H035C/035M/HS035M/H035M 0.31 megapixel mode: 640 (H) × 480 (V), approx. 0.31 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels • CA-H048CX/H048MX 0.47 megapixel mode: 784 (H) × 596 (V), approx. 0.47 megapixels 0.31 megapixel mode: 640 (H) × 480 (V), approx. 0.31 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels
Main imag	e processor	DSP (Fast type)	1000 (1) × 1200 (1), approx. 1.02 megapixolo	DSP	
Program m	nemory	Up to 1000 settings (depend	ing on SD card capacity and setting contents) for \$	SD card 1 and SD card 2 individually and externa	I switching is possible
Screen cap	acity	Maximum 1000 screens for each program (depending on SD c			
Memory ca	ard	• SD card s Supports OP-87133 (512 MB), CA-SD1G (1 G CA-SD4G (4 GB), and C	GB: standard equipment on the SD1 slot), CA-SD16G (16 GB)	Supports OP-87133 (512 MB: sta	rd slot × 2 Indard equipment on the SD1 slot), 4 GB), and CA-SD16G (16 GB)
Image archive		With area camera connected: • Max. 12757 images (monochrome camera, 0.24 megapixels) • Max. 10221 images (monochrome camera, 0.31 megapixels) • Max. 1630 images (monochrome camera, 0.47 megapixels) • Max. 1638 images (monochrome camera, 2 megapixels) • Max. 1638 images (monochrome camera, 5 megapixels) • Max. 19441 images (colour camera, 0.24 megapixels) • Max. 6609 images (colour camera, 0.31 megapixels) • Max. 1638 images (colour camera, 0.31 megapixels) • Max. 583 images (colour camera, 2 megapixels)		 Max. 4091 images (monochrome camera, 0.24 megapixels) 	 Max. 2181 images (monochrome camera, 0.24 megapixels
	Assignable input	• 20 connection points (including four high-speed terr	ninals that can be assigned to trigger input) • Inp	put rating: 26.4 V or lower, or 1.2 mA or greater (:	2.2 mA or greater for high-speed input terminals
	Assignable output	• 28 connection points (including four	high-speed terminals that can be assigned to exter		FET*1: Max. 50 mA (30 V or less)
	Monitor output		Analogue RGB output, XGA (10	· · · · · · · · · · · · · · · · · · ·	
	Unit indicators	5	Power, ERROR LE		2
	PLC link	Mitsubishi Electric: MEL	ontrol input/output using the Ethernet or RS-232C • The following PLCs are sup KEYENCE: KV-8000/7000/5000/3000/1 .SEC iQ-R/L/Q Series, MELSEC A Series, (RS-232 IRON: SYSMAC CJ2/CJ1/CST Series, SYSMAC C YASKAWA Electric Corporation: MP2000 S	port (Cannot be used in conjunction with CC-Lir pported via link unit*?: 1000/700 Series, KV Nano Series 2C only), MELSEC iQ-F Series, MELSEC FX Serie Series (RS-232C only), SYSMAC CP1 Series eries/MP900 Series (RS-232C only)	nk, EtherNet/IP®, PROFINET, EtherCAT®) es (RS-232C only)
	Ethernet	download inspection settings, p	inpurputuhut - Connecting to RETENCE PC app erform a variety of simulations, send and receive a n SFTP Client function, a VNC server function (for - Jumbo frame support (when connected	a variety of data including image data, and use the non-PC clients, only displaying the monitor scre	remote desktop function.
	USB	Connecting to KEYENCE PC application softwar send and rec	e makes it possible to output numerical values, pe eive a variety of data including image data, and us	erform control I/O, upload and download inspection	on settings, perform a variety of simulations,
nterface	CC Link	By connecting the optional CC-Li	nk unit CA-NCL20E, numerical value output and c	control input/output are enabled (Cannot be used	
	CC-Link EtherCAT®	Eth Connecting the optional EtherCAT® unit (erNet/IP®, PROFINET or EtherCAT®) • Supports CA-NEC20E enables numerical value output and communication) (Input: max. 536 bytes, output: max.	ver. 1.10 and ver. 2.00 remote device stations ontrol I/O (Cannot be used in conjunction with Plax. 532 bytes) • Message communication (non-	C-Link, EtherNet/IP®, or PROFINET.)
	EtherNet/IP®	PROFINI	Explicit Device Identification Confo put/output enabled via the Ethernet port or optiona et or EtherCAT®) Supports cyclic communication	II CA-NEP20E EtherNet/IP® unit (Cannot be used ion (max. 1436 bytes) and message communicati	on
		 Numerical data input/output and control in) / 1: Exclusive Owner, 4: Input Only (CA-NEP20E; put/output enabled via the Ethernet port or option: lic communication (max. 1408 bytes (Ethernet no	al CA-NPN20E PROFINET unit (Cannot be used i rt) / 1248 bytes (CA-NPN20E)) • Supports non-	n conjunction with PLC-link, CC-Link,
	PROFINET	Etherweight , or EtheroArt) • Supports cyt			
		Enterweight , or EnteroAr) • Supports cyc	 Conforms to Conformance Class A (
	SNTP		Conforms to Conformance Class A (Unit's date and time auto-corrects when	unit is connected to SNTP server	o console buttons
			 Conforms to Conformance Class A (unit is connected to SNTP server 1983) • Supports the assignment of operations t	o console buttons
	SNTP USB console Mouse		Conforms to Conformance Class A (Unit's date and time auto-corrects when vious menus via an optional USB console (OP-87 Possible to control various menus via an op anel using the RS-232C port (Cannot be used in cr	unit is connected to SNTP server 983) • Supports the assignment of operations to obtain a dedicated mouse (OP-87506) onjunction with RS-232C no-protocol communic	
	SNTP USB console Mouse Touch panel	Possible to control va Settings can be operated from a CA Series touch pa	Conforms to Conformance Class A (Unit's date and time auto-corrects when irious menus via an optional USB console (OP-87 Possible to control various menus via an optional using the RS-232C port (Cannot be used in cut	unit is connected to SNTP server 983) • Supports the assignment of operations to otional dedicated mouse (OP-87506) onjunction with RS-232C no-protocol communic ous and operation buttons	ation, PLC links using RS-232C, or EtherCAT®)
	SNTP USB console Mouse	Possible to control value Settings can be operated from a CA Series touch pale By connecting the HDD (max.)	Conforms to Conformance Class A (Unit's date and time auto-corrects when rious menus via an optional USB console (OP-87 Possible to control various menus via an optional using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control	unit is connected to SNTP server 983) • Supports the assignment of operations to stional dedicated mouse (0P-87506) onjunction with RS-232C no-protocol communic sus and operation buttons .0, bus-powered, rated output 900 mA), image an	ation, PLC links using RS-232C, or EtherCAT®)
	SNTP USB console Mouse Touch panel USB HDD	Possible to control value Settings can be operated from a CA Series touch pale. By connecting the HDD (max. Japa	Conforms to Conformance Class A (Unit's date and time auto-corrects when trious menus via an optional USB console (OP-87 Possible to control various menus via an op anel using the RS-232C port (Cannot be used in cr	unit is connected to SNTP server 983) • Supports the assignment of operations to titional dedicated mouse (0P-87506) onjunction with RS-232C no-protocol communic russ and operation buttons 0, bus-powered, rated output 900 mA), image an ese/German (initial language set at first startup)	ation, PLC links using RS-232C, or EtherCAT®) d other data can be output
llumination	SNTP USB console Mouse Touch panel USB HDD	Possible to control value Settings can be operated from a CA Series touch pale By connecting the HDD (max. Japa By connecting the option	Conforms to Conformance Class A (Unit's date and time auto-corrects when rious menus via an optional USB console (OP-87 Possible to control various menus via an optional using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control using the RS-232C port (Cannot be used in control	unit is connected to SNTP server 983) • Supports the assignment of operations to titional dedicated mouse (0P-87506) online of the state of the sta	ation, PLC links using RS-232C, or EtherCAT®) d other data can be output
llumination Cooling fan	SNTP USB console Mouse Touch panel USB HDD	Possible to control value Settings can be operated from a CA Series touch pale. By connecting the HDD (max. Japa	Conforms to Conformance Class A (Unit's date and time auto-corrects when trious menus via an optional USB console (OP-87 Possible to control various menus via an op anel using the RS-232C port (Cannot be used in cr	unit is connected to SNTP server 983) • Supports the assignment of operations to stional dedicated mouse (OP-87506) onjunction with RS-232C no-protocol communic sus and operation buttons .0, bus-powered, rated output 900 mA), image an ese/German (initial language set at first startup) , lighting and intensity control for the LED illumin None	ation, PLC links using RS-232C, or EtherCAT®) d other data can be output
llumination Cooling fan	SNTP USB console Mouse Touch panel USB HDD	Possible to control value Settings can be operated from a CA Series touch pale By connecting the HDD (max. Japa By connecting the option	Conforms to Conformance Class A (Unit's date and time auto-corrects when trious menus via an optional USB console (OP-87 Possible to control various menus via an optional using the RS-232C port (Cannot be used in cu	unit is connected to SNTP server 983) • Supports the assignment of operations to stional dedicated mouse (OP-87506) onjunction with RS-232C no-protocol communic sus and operation buttons .0, bus-powered, rated output 900 mA), image an ese/German (initial language set at first startup) , lighting and intensity control for the LED illumin None	ation, PLC links using RS-232C, or EtherCAT®) d other data can be output
Language Illuminatior Cooling fan Rating	SNTP USB console Mouse Touch panel USB HDD n control	Possible to control value Settings can be operated from a CA Series touch pale By connecting the HDD (max. Japa By connecting the option	Conforms to Conformance Class A (Unit's date and time auto-corrects when rious menus via an optional USB console (OP-87 Possible to control various menus via an optional USB console (OP-87 Possible to control various menus via an optional USB nessed in composition of Supports USB 3. Supports dedicated touch mer 2 TB) to the dedicated USB port (supports USB 3. nesse/English/Simplified Chiness/Traditional Chinal light expansion unit CA-DC40E/DC50E/DC60E, 24 VDC ±1 3.8 A 0 to 45°C (when installed on a DIN rail)/0 tr	unit is connected to SNTP server 983) • Supports the assignment of operations to stional dedicated mouse (0P-87506) onjunction with RS-232C no-protocol communic us and operation buttons .0, bus-powered, rated output 900 mA), image an ese/German (initial language set at first startup) lighting and intensity control for the LED illumin None 0% 0 40°C (when installed on a surface)	ation, PLC links using RS-232C, or EtherCAT®) d other data can be output ation is possible.*3
Illumination Cooling fan Rating	SNTP USB console Mouse Touch panel USB HDD n control Voltage Current consumption	Possible to control value Settings can be operated from a CA Series touch pale By connecting the HDD (max. Japa By connecting the option	Conforms to Conformance Class A (Unit's date and time auto-corrects when rious menus via an optional USB console (OP-87 Possible to control various menus via an op anel using the RS-232C port (Cannot be used in cu	unit is connected to SNTP server 983) • Supports the assignment of operations to stional dedicated mouse (0P-87506) onjunction with RS-232C no-protocol communic us and operation buttons .0, bus-powered, rated output 900 mA), image an ese/German (initial language set at first startup) lighting and intensity control for the LED illumin None 0% 0 40°C (when installed on a surface)	ation, PLC links using RS-232C, or EtherCAT® d other data can be output ation is possible.*3

^{*1} Positive common connections supporting NPN input devices and negative common connections supporting PNP input devices are both possible. *2 Models equipped with the Ethernet port in the CPU unit support Ethernet port direct connection. *3 Up to 8 light control expansion units can be connected (max. two CA-DC50E/DC60E units out of 8).

	r (XG-X2800)					
Model			X2800			
Camera inp	ut*1	With area camera input unit CA-E100 connected: 2 colour/monochrome cameras per CA-E100, up to 4 cameras via a maximum of 2 units can be connected. With line scan cameras or two monochrome/colour cameras per CA-E100L, 4 cameras max. with 2 camera input units With high-speed line scan cameras unit CA-E200L connected: 2 high-speed line scan cameras per CA-E200L, 4 cameras max. with 2 camera input units	With XR camera input unit CA-E100T connected: 13D camera per CA-E100T, 2 cameras max. with 2 camera input units With XT camera input unit CA-E200T connected: 1 XT camera per CA-E200T, 2 cameras max. with 2 camera input units			
	Trigger input	Simultaneous/individual capture with up to 4 cameras/heads can be selected (up to	2 cameras/heads for simultaneous capture when one camera input unit is connected)			
Supported cameras/ Number of pixels	Area camera High-speed line scan	CA-035C/HS035C/H035C/035M/HS035M/H035M O 31 megapixel mode: 640 (H) × 480 (V), approx. 0.31 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels CA-H046CX/H048MX 0.47 megapixel mode: 784 (H) × 596 (V), approx. 0.47 megapixels 0.31 megapixel mode: 640 (H) × 480 (V), approx. 0.31 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels CA-200C/HS200C/H200C/200M/HS200M/H200M 2 megapixel mode: 1600 (H) × 1200 (V), approx. 1.92 megapixels 1 megapixel mode: 1024 (H) × 960 (V), approx. 0.98 megapixels CA-HL08MX 8192 (H) × 8192 (L), approx. 6.7.11 megapixels	CA-H200CX/H200MX 2 megapixel mode: 1600 (H) × 1200 (V), approx. 1.92 megapixels CA-H500C/H500M 5 megapixel mode: 2432 (H) × 2050 (V), approx. 4.99 megapixels CA-H500CX/H500MX 5 megapixel mode: 2432 (H) × 2040 (V), approx. 4.96 megapixels 2 megapixel mode: 1600 (H) × 1200 (V), approx. 1.92 megapixels CA-HF2100C/HF2100M 21 megapixel mode: 5104 (H) × 4092 (V), approx. 20.89 megapixels 5 megapixel mode: 2432 (H) × 2050 (V), approx. 4.99 megapixels 6 CA-HL020MX 2048 (H) × 16384 (L), approx. 33.55 megapixels CA-HL020MX 2048 (H) × 16384 (L), approx. 33.55 megapixels			
	xR camera	CA-HL04MX 4096 (H) × 16384 (L), approx. 67.11 megapixels XR-HT40M 2048 (H) × 2048 (L), approx. 4.19 megapixels	• XR-HT15M 1408 (H) × 1408 (L), approx. 1.98 megapixels			
	XT camera		2 (V), approx. 9.44 megapixels			
Main image	•	`	Fast type)			
Program m	emory) for SD card 1 and SD card 2 individually and external switching is possible			
Screen cap	acity		, Support for image registration and partial image registration from a position-corrected image, eaccording to variables.			
Memory ca	rd		indard equipment on the SD1 slot), CA-SD4G (4 GB), and CA-SD16G (16 GB)			
Image			s an archive to the image memory of the main unit			
archive	Area camera	Max. 12757 images (monochrome camera, 0.24 megapixels) Max. 10221 images (monochrome camera, 0.31 megapixels) Max. 6730 images (monochrome camera, 0.47 megapixels) Max. 1638 images (monochrome camera, 2 megapixels) Max. 613 images (monochrome camera, 5 megapixels) Max. 613 images (monochrome camera, 2 megapixels) Max. 122 images (monochrome camera, 21 megapixels)	Max. 12441 images (colour camera, 0.24 megapixels) Max. 9998 images (colour camera, 0.31 megapixels) Max. 6609 images (colour camera, 0.47 megapixels) Max. 1598 images (colour camera, 2 megapixels) Max. 583 images (colour camera, 5 megapixels) Max. 110 images (colour camera, 2 megapixels)			
	Line Scan Camera	Max. 71 images (CA-HL02MX continuous capture, 2048 × 16384 pixels) Max. 151 images (CA-HL02MX continuous capture, 2048 × 8192 pixels) Max. 71 images (CA-HL02MX individual capture, 2048 × 16384 pixels) Max. 31 images (CA-HL04MX continuous capture, 4096 × 16384 pixels)	Max. 68 images (CA-HL04MX continuous capture, 4096 × 8192 pixels) Max. 31 images (CA-HL04MX individual capture, 4096 × 16384 pixels) Max. 28 images (CA-HL08MX continuous capture, 8192 × 8192 pixels) Max. 31 images (CA-HL08MX individual capture, 8192 × 8192 pixels)			
	XR camera	Max. 494 images (XR 15 mm type, height image and greyscale image saved) Max. 2028 images (XR 15 mm type, binning: ON, height image and greyscale image saved)	 Max. 220 images (XR 40 mm type, height image and greyscale image saved) Max. 953 images (XR 40 mm type, binning: ON, height image and greyscale image saved) 			
	XT camera	Max. 192 images (XT-024/060, binning ON, or binning OFF with narrow field of view)	Max. 40 images (XT-024/060, binning OFF, or binning ON with expansion)			
	Assignable input	1 (0 0 1 0 00 1 7	• Input rating: 26.4 V or lower, or 1.2 mA or greater (2.2 mA or greater for high-speed input terminals			
	Assignable output		external trigger-linked FLASH output) • Photo MOSFET*2: Max.50 mA (30 V or less)			
	Encoder input	 When the CA-E100L/E200L is connected: 2 inputs per unit, 4 inputs total for 2 units max. RS-422 line-driver output (Multi-drop support*3, Supports 5 V output included: max. 150 mA) and open collector output (24 V devices only with CA-E100L/E200L) included 				
	Monitor output	Analogue RGB output, XGA (1024 × 768, 24-bit colour)				
	Unit indicators	Power, ERROR LED display				
	RS-232C		Series touch panel interface (Cannot be used in conjunction with PLC links using RS-232C) n baud rate of 230400 bps			
	PLC link	● The following PLCs a KEYENCE: KV-8000/7000/5000/3 Mitsubishi Electric: MELSEC iQ-R/L/Q Series, MELSEC A Series, (R OMRON: SYSMAC CJ2/CJ1/CS1 Series, SYSM	232C port (Cannot be used in conjunction with CC-Link, EtherNet/IP®, PROFINET, EtherCAT®) re re supported via link unit**. 2000/1000/700 Series, KV Mano Series 5-232C only), MELSEC iO-F Series, MELSEC FX Series (RS-232C only) ACC Series (RS-232C only), SYSMAC CP1 Series (RS-232C only) Series (RS-232C only), SYSMAC CP1 Series (RS-232C only)			
	Ethernet	Can output numerical values and perform control input/output Connecting to KEYENCE PC download inspection settings, perform a variety of simulations, send and rec Supports FTP client functions, an SFTP Client function, a VNC serve function	Capplication software enables not only the above functions but also makes it possible to upload and eive a variety of data including image data, and use the remote desktop function. I (for non-PC clients, only displaying the monitor screen is supported), and a BOOTP function lected to CA-NEC20E/NEP20E/NPN20)			
Interface	USB	send and receive a variety of data including image data, ar	es, perform control I/O, upload and download inspection settings, perform a variety of simulations, nd use the remote desktop function. • Dedicated to USB 2.0			
	CC-Link	(Cannot be used in conjunction with PLC- • Supports ver. 1.10 and v	numerical value output and control input/output are enabled Link, EtherNet/IP®, PROFINET or EtherCAT®) er. 2.00 remote device stations			
	EtherCAT®	 Process data object communication (cyclic communication) (Input: max. 536 by 	ol input/output (Cannot be used in conjunction with PLC-Link, CC-Link, EtherNet/IP®, or PROFINET.) tes, output: max. 532 bytes) ◆ Message communication (non-cyclic communication) tion ◆ Conforms to conformance test V2.1.0.2.			
	EtherNet/IP®	PROFINET or EtherCAT®) • Supports cyclic commu • Maximum connections: 32 (Ethernet port) / 1: Exclusive Owner, 4: Input Only (CA-NEI	tional CA-NEP20E EtherNet/IP® unit (Cannot be used in conjunction with PLC-link, CC-Link, nication (max. 1436 bytes) and message communication *20E) • Conforms to conformance test Version CT15 (Ethernet port) / CT16 (CA-NEP20E)			
	PROFINET	EtherNet/IP®, or EtherCAT®) • Supports cyclic communication (max. 1408 bytes (Ethern	ptional CA-NPN20E PR0FINET unit (Cannot be used in conjunction with PLC-link, CC-Link, et port) / 1248 bytes (CA-NPN20E)) ■ Supports non-cyclic communication (recorded data) s A (Ethernet port) / C (CA-NPN20E)			
	SNTP		when unit is connected to SNTP server			
	USB console		via an optional USB console (OP-87983)			
			of operations to console buttons			
	Mouse Touch panel	Settings can be operated from a CA Series touch panel using the RS-232C port (Cannot b)	an optional dedicated mouse (0P-87506) e used in conjunction with RS-232C no-protocol communication or PLC links using RS-232C)			
	· .		n menus and operation buttons			
Langue	USB HDD		SB 3.0, bus-powered, rated output 900 mA), image and other data can be output			
Language	control		Chinese/German (initial language set at first startup) 260E, lighting and intensity control for the LED illumination is possible.*5			
	I OUTILI OF		ed (attached) to the controller.			
Illumination						
Illumination Cooling fan						
Illumination	Voltage Current consumption	24 VI	05 (allamon) to the controller. (0.5 ±10%) (3.3 Å			
Illumination Cooling fan Rating Environmental	Voltage Current consumption Operating ambient temperature	24 VE 5 0 to 45°C (when installed on a DIN rai	OC ±10% .3 A 1)/0 to 40°C (when installed on a surface)			
Illumination Cooling fan Rating	Voltage Current consumption	24 VE 5 0 to 45°C (when installed on a DIN rai 35 to 85% RH	OC ±10% .3 A			

^{*1} At least one camera input unit is required (controller has no built-in camera inputs). *2 The output common can be configured for NPN or PNP input devices.
*3 Supported on the CA-E100L/E200L. *4 Models equipped with the Ethernet port in the CPU unit support Ethernet port direct connection. *5 Up to 8 light control expansion units can be connected (max. two CA-DC50E/DC60E units out of 8).

Controller (XG-X2900)

	r (XG-X2900)					
Model		XG- ■ With area camera input unit CA-E100 connected:	• With XR camera input unit CA-E100T connected:			
Camera inp	ut*1	2 colour/monochrome cameras per CA-E100, up to 4 cameras via a maximum of 2 units can be connected. With line scan camera input unit CA-E100L connected: 2 line scan cameras or two monochrome/colour cameras per CA-E100L, 4 cameras max. with	With An Camera input unit CA-E-TOOT conflected: 13D camera per CA-E100T, 2 cameras max. with 2 camera input units With XT camera input unit CA-E200T connected: 1 XT camera per CA-E200T, 2 cameras max. with 2 camera input units			
		2 camera input units With high-speed line scan camera unit CA-E200L connected: 2 high-speed line scan cameras per CA-E200L, 4 cameras max. with 2 camera input units				
	Trigger input		o 2 cameras/heads for simultaneous capture when one camera input unit is connected)			
Supported cameras/ Number of bixels	Area camera		 CA-H500C/H500M 5 megapixel mode: 2432 (H) × 2050 (V), approx. 4.99 megapixels CA-H500CX/H500MX 5 megapixel mode: 2432 (H) × 2040 (V), approx. 4.96 megapixels 2 megapixel mode: 1600 (H) × 1200 (V), approx. 1.92 megapixels CA-HF2100C/HF2100M 21 megapixel mode: 5104 (H) × 4092 (V), approx. 20.89 megapixels 5 megapixel mode: 2432 (H) × 2050 (V), approx. 4.99 megapixels CA-HF6400C/HF6400M 64 megapixel mode: 8192 (H) × 7808 (V), approx. 63.96 megapixels 41 megapixel mode: 7168 (H) × 5768 (V), approx. 41.35 megapixels 21 megapixel mode: 5104 (H) × 4092 (V), approx. 20.89 megapixels 			
	High-speed line scan	• CA-HL08MX 8192 (H) × 8192 (L), approx. 67.11 megapixels	• CA-HL02MX 2048 (H) × 16384 (L), approx. 33.55 megapixels			
	camera	• CA-HL04MX 4096 (H) × 16384 (L), approx. 67.11 megapixels				
	XR camera	• XR-HT40M 2048 (H) × 2048 (L), approx. 4.19 megapixels	 XR-HT15M 1408 (H) × 1408 (L), approx. 1.98 megapixels 			
	XT camera	• XT-024/060 3072 (H) × 30	072 (V), approx. 9.44 megapixels			
Aain image	processor	DSP (Fast type)			
Program m	emory	Up to 1000 settings (depending on SD card capacity and setting contents) for SD card 1 and SD card 2 individually and external switching is possible			
Screen cap	acity		gistration and partial image registration from a position-corrected image, Externally switchable according to variab			
Memory ca	rd	• SD card slot × 2 • Supports OP-87133 (512 MB), CA-SD1G (1 GB), C	A-SD4G (4 GB: standard equipment on the SD1 slot), and CA-SD16G (16 GB)			
lmage		Can store the image amounts listed below as	an archive to the image memory of the main unit			
archive	Area camera	Max. 29005 images (monochrome camera, 0.24 megapixels) Max. 23241 images (monochrome camera, 0.31 megapixels) Max. 15306 images (monochrome camera, 0.47 megapixels) Max. 3732 images (monochrome camera, 2 megapixels) Max. 1421 images (monochrome camera, 5 megapixels) Max. 307 images (monochrome camera, 21 megapixels)	Max. 28297 images (colour camera, 0.24 megapixels) Max. 22744 images (colour camera, 0.31 megapixels) Max. 15043 images (colour camera, 0.47 megapixels) Max. 3675 images (colour camera, 2 megapixels) Max. 1386 images (colour camera, 5 megapixels) Max. 292 images (colour camera, 21 megapixels)			
_	Line Scan Camera	Max. 185 images (CA-HL02MX continuous capture, 2048 × 6384 pixels) Max. 387 images (CA-HL02MX continuous capture, 2048 × 8192 pixels) Max. 185 images (CA-HL02MX individual capture, 2048 × 16384 pixels) Max. 88 images (CA-HL04MX, continuous capture, 4096 × 16384 pixels)	Max. 182 images (CA-HL04MX continuous capture, 4096 x 8192 pixels) Max. 88 images (CA-HL04MX individual capture, 4096 x 16384 pixels) Max. 85 images (CA-HL08MX continuous capture, 8192 x 8192 pixels) Max. 88 images (CA-HL08MX individual capture, 8192 x 8192 pixels)			
	XR camera	Max. 1170 images (XR 15 mm type, height image and greyscale image saved)	Max. 540 images (XR 40 mm type, height image and greyscale image saved)			
		Max. 4729 images (XR 15 mm type, binning: ON, height image and greyscale image saved)	Max. 2231 images (XR 40 mm type, binning: ON, height image and greyscale image saved)			
	XT camera	Max. 534 images (XT-024/060, binning ON, or binning OFF with narrow field of view)	Max. 125 images (XT-024/060, binning OFF, or binning ON with expansion)			
	Assignable input	• 20 connection points (including four high-speed terminals that can be assigned to trigger input)				
	Assignable output		o external trigger-linked FLASH output) • Photo MOSFET*2: Max.50 mA (30 V or less)			
	Encoder input		2 inputs per unit, 4 inputs total for 2 units max.			
	Monitor output	RS-422 line-driver output (Multi-drop support*3, Supports 5 V output included: max. 150 mA) and open collector output (24 V devices only with CA-E100L/E200L) included Analogue RGB output, XGA (1024 × 768, 24-bit colour)				
	Unit indicators		OR LED display			
			Series touch panel interface (Cannot be used in conjunction with PLC links using RS-232C)			
	RS-232C	Supports a maximur	to baud rate of 230400 bps et port (Cannot be used in conjunction with CC-Link, EtherNet/IP®, PROFINET or EtherCAT®)			
	PLC link	KEYENCE: KV-8000/7000/5000/3 Mitsubishi Electric: MELSEC iQ-R/L/Q Series, MELSEC A Series, (R:	re supported via link unit**: 05-2000/700 Series, KV Nano Series 5-232C only), MELSEC 10-F Series, MELSEC FX Series (RS-232C only) CP1 Series 'YASKAWA Electric Corporation: MP2000 Series/MP900 Series (RS-232C only)			
	Ethernet	download inspection settings, perform a variety of simulations, send and rec Supports FTP client and server functions, an SFTP Client function, a VNC server function Jumbo frame support (when conr	C application software enables not only the above functions but also makes it possible to upload an eive a variety of data including image data, and use the remote desktop function. If (for non-PC clients, only displaying the monitor screen is supported), and a BOOTP function nected to CA-NEC20E/NEP20E/NPN20)			
nterface	USB		erform control I/O, upload and download inspection settings, perform a variety of simulations, send se the remote desktop function. • Dedicated to USB 2.0 ufout are enabled (Cannot be used in conjunction with PLC-Link, EtherNet/IP®, PROFINET or EtherCA			
	CC-Link	Supports ver. 1.10 and v Connecting the optional EtherCAT® unit CA-NEC20E enables numerical value output and contr	er. 2.00 remote device stations ol input/output (Cannot be used in conjunction with PLC-Link, CC-Link, EtherNet/IP® or PROFINET			
	EtherCAT®	Supports CoE	tes, output: max. 532 bytes) • Message communication (non-cyclic communication) tition • Conforms to conformance test V2.1.0.2. ptional CA-NEP20E EtherNet/IP® unit (Cannot be used in conjunction with PLC-link, CC-Link,			
	EtherNet/IP®	PROFINET or EtherCAT®) • Supports cyclic commu • Maximum connections: 32 (Ethernet port) / 1: Exclusive Owner, 4: Input Only (CA-NEI	nication (max. 1436 bytes) and message communication P20E) • Conforms to conformance test Version.CT15 (Ethernet port) / CT16 (CA-NEP20E) otional CA-NPN20E PROFINET unit (Cannot be used in conjunction with PLC-link, CC-Link,			
	PROFINET	EtherNet/IP®, or EtherCAT®) • Supports cyclic communication (max. 1408 bytes (Ethern • Conforms to Conformance Clas	tet port) / 1248 bytes (CA-NPN20E)) • Supports non-cyclic communication (recorded data) ss A (Ethernet port) / C (CA-NPN20E)			
	SNTP		when unit is connected to SNTP server			
	USB console		via an optional USB console (OP-87983)			
			of operations to console buttons an optional dedicated mouse (OP-87506)			
	Mouse Touch panel	Settings can be operated from a CA Series touch panel using the RS-232C port (Cannot by	an optional dedicated mouse (OF-67506) be used in conjunction with RS-232C no-protocol communication or PLC links using RS-232C) h menus and operation buttons			
	USB HDD		ISB 3.0, bus-powered, rated output 900 mA), image and other data can be output			
.anguage	1000 HDD		Chinese/German (initial language set at first startup)			
.anguage Ilumination	control		Chinese/German (initial ranguage set at hist startup) C60E, lighting and intensity control for the LED illumination is possible.*5			
nummatioi		, , , , , , , , , , , , , , , , , , , ,				
online f-			led (attached) to the controller. DC ±10%			
Cooling fan	Voltage					
	Current cor	1 5	5.3 A			
	Current consumption					
Rating	Current consumption Operating ambient temperature		il)/0 to 40°C (when installed on a surface)			
Cooling fan Rating Environmental resistance	Operating ambient	0 to 45°C (when installed on a DIN rai	il)/0 to 40°C (when installed on a surface) (no condensation)			

^{*1} At least one camera input unit is required (controller has no built-in camera inputs). *2 The output common can be configured for NPN or PNP input devices.
*3 Supported on the CA-E100L/E200L. *4 Models equipped with the Ethernet port in the CPU unit support Ethernet port direct connection. *5 Up to 8 light control expansion units can be connected (max. two CA-DC50E/DC60E units out of 8).

Controller (XG-X1500/XG-X1200/XG-X1000)

Model		XG-X1500	XG-X1200	XG-X1000			
Camera in	out		neras Up to 4 inputs can be connected by connecting 1 optional are				
	Trigger input		to 4 cameras can be selected (up to 2 cameras for simultaneous cap	oture when the CA-E100 is not connected)			
Supported Number of	cameras/ pixels	 CA-035C/HS035C/H035C/035M/HS035M/H035M 0.31 megapixel mode: 640 (H) × 480 (V), approx. 0.31 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels CA-H048CX/H048MX 0.47 megapixel mode: 784 (H) × 596 (V), approx. 0.31 megapixels 0.31 megapixels 0.31 megapixels 0.31 megapixels 0.24 megapixels 0.24 megapixel 0.24 megapixel 0.24 megapixel CA-200C/HS200C/200M/HS200M/H200M 2 megapixel mode: 6100 (H) × 1200 (V), approx. 1.92 megapixels 1 megapixel mode: 1000 (H) × 1200 (V), approx. 1.92 megapixels CA-H200CX/H200MX 2 megapixel mode: 1600 (H) × 1200 (V), approx. 1.92 megapixels CA-H500C/H500M 5 megapixel mode: 4242 (H) × 2050 (V), approx. 4.99 megapixels CA-H500CX/H500MX 5 megapixel mode: 4242 (H) × 2040 (V), approx. 4.96 megapixels CA-H500CX/H500MX 5 megapixel mode: 4242 (H) × 2040 (V), approx. 4.96 megapixels 2 megapixel mode: 1600 (H) × 1200 (V), approx. 4.96 megapixels 	CA-035C/HS035C/H035C/035M/HS035M/H035M 0.31 megapixel mode: 640 (H) × 480 (V), approx. 0.31 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels CA-H048CX/H048MX 0.47 megapixel mode: 784 (H) × 596 (V), approx. 0.47 megapixels 0.31 megapixel mode: 640 (H) × 480 (V), approx. 0.31 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels 1 CA-200C/HS200C/H200C/200M/HS200M/H200M 2 megapixel mode: 1600 (H) × 1200 (V), approx. 192 megapixels 1 megapixel mode: 1024 (H) × 960 (V), approx. 0.98 megapixels 0.4-H200CX/H200MX 2 megapixel mode: 1600 (H) × 1200 (V), approx. 1.92 megapixels	CA-035C/HS035C/H035C/035M/HS035M/H035M 0.31 megapixel mode: 640 (H) × 480 (V), approx. 0.31 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels CA-H048CX/H048MX 0.47 megapixel mode: 784 (H) × 596 (V), approx. 0.47 megapixels 0.31 megapixels 0.24 megapixel mode: 640 (H) × 480 (V), approx. 0.31 megapixels 0.24 megapixel mode: 512 (H) × 480 (V), approx. 0.24 megapixels			
lain imag	e processor		DSP				
Program n	nemory		ard capacity and setting contents) for SD card 1 and SD card 2 indiv				
Screen cap	acity	Maximum 1000 screens for each program (depending on S	SD card size), Image compression, Support for image registration an Externally switchable according to variables.	d partial image registration from a position-corrected image,			
Memory ca		SD card slot × 2 Supports OP-87133 (512 MB), CA-SD1G (1 GB: standard equipment on the SD1 slot), CA-SD4G (4 GB), and CA-SD16G (16 GB)	SD ca Supports OP-87133 (512 MB: standard equipment on the SD1 standard equipment of the SD	rd slot × 2 (liot), CA-SD1G (1 GB), CA-SD4G (4 GB), and CA-SD16G (16 GB			
lmage arch	nive	Can store the image amounts listed below as an archive to the image Max. 7341 images (monochrome camera, 0.24 megapixels)	ge memory of the main unit	T			
		Max. 3871 images (monochrome camera, 0.47 megapixels) Max 939 images (monochrome camera, 2 megapixels) Max. 341 images (monochrome camera, 5 megapixels) Max. 7156 images (colour camera, 0.24 megapixels) Max. 5749 images (colour camera, 0.31 megapixels) Max. 3798 images (colour camera, 0.47 megapixels) Max. 305 images (colour camera, 2 megapixels) Max. 315 images (colour camera, 5 megapixels)	Max. 1541 images (monochrome camera, 0.31 megapixels) Max. 1012 images (monochrome camera, 0.47 megapixels) Max. 241 images (monochrome camera, 2 megapixels) Max. 1871 images (colour camera, 0.24 megapixels) Max. 1501 images (colour camera, 0.31 megapixels) Max. 987 images (colour camera, 0.47 megapixels) Max. 213 images (colour camera, 2 megapixels)	Max. 1098 images (monochrome camera, 0.24 megapixels) Max. 878 images (monochrome camera, 0.31 megapixels) Max. 576 images (monochrome camera, 0.47 megapixels) Max. 1065 images (colour camera, 0.24 megapixels) Max. 852 images (colour camera, 0.31 megapixels) Max. 558 images (colour camera, 0.47 megapixels)			
	Assignable input	• 20 connection points (including four high-speed terminals that of	can be assigned to trigger input) • Input rating: 26.4 V or lower, or	1.2 mA or greater (2.2 mA or greater for high-speed input termina			
	Assignable output Monitor output Unit indicators	• 28 connection points (including four high-speed terminals that can be assigned to external trigger-linked FLASH output) • Photo MOSFET*1: Max. 50 mA (30 V or less) Analogue RGB output, XGA (1024 × 768, 24-bit colour) Power, ERROR LED display					
		Functionality switchable between numerical data output, control input/output, and CA Series touch panel interface (Cannot be used in conjunction with PLC links using RS-232C)					
	RS-232C	·	Supports a maximum baud rate of 230400 bps				
	PLC link	K Mitsubishi Electric: MELSEC iQ-R/L OMRO	put/output using the Ethernet or RS-232C port (Cannot be used in c • The following PLCs are supported via link unit**: EYENCE: KV-8000/7000/5000/3000/1000/700 Series, KV Nano Ser //O Series, MELSEC A Series, (RS-232C only), MELSEC iO-F Series N: SYSMAC CJ2/CJ1/CS1/CP1 Series, SYSMAC C Series (RS-232 AWA Electric Corporation: MP2000 Series, MP900 Series (RS-232)	ies 5, MELSEC FX Series (RS-232C only) 1C only)			
	Ethernet	download inspection settings, perform a var • Supports FTP client and server functions, an SFTP Clien	t • Connecting to KEYENCE PC application software enables not of lety of simulations, send and receive a variety of data including iman function, a VNC server function (for non-PC clients, only display) Jumbo frame support (when connected to CA-NEC20E/NPPOEC/NPT	ge data, and use the remote desktop function. ng the monitor screen is supported), and a BOOTP function			
	USB	Connecting to KEYENCE PC application software makes it p	ossible to output numerical values, perform control I/O, upload and	download inspection settings, perform a variety of simulations,			
nterface	CC-Link		y of data including image data, and use the remote desktop function rical value output and control input/output are enabled (Cannot be ι				
	OU-LIIIK	Numerical data input/output and control input/output as	 Supports ver. 1.10 and ver. 2.00 remote device stations nabled via the Ethernet port or optional CA-NEP20E EtherNet/IP® ur 	it (Cannot be used in conjunction with DLC link CC Link			
	EtherNet/IP®	PROFINET or EtherC	AT®) • Supports cyclic communication (max. 1436 bytes) and me	ssage communication			
			ive Owner, 4: Input Only (CA-NEP20E) • Conforms to conformance of the Ethernet port or optional CA-NPN20E PROFINET unit				
	PROFINET	EtherNet/IP®, or EtherCAT®) • Supports cyclic commun	incation (max. 1408 bytes (Ethernet port) / 1248 bytes (CA-NPN20E Conforms to Conformance Class A (Ethernet port) / C (CA-NPN20E Conforms to Conformance Class A (Ethernet port) / C (CA-NPN20E	Supports non-cyclic communication (recorded data) E)			
	EtherCAT®	Process data object communication (cyclic communica	tion) (Input: max. 536 bytes, output: max. 532 bytes) • Message co Explicit Device Identification • Conforms to conformance test V2.1	mmunication (non-cyclic communication) • Supports CoE .0.2.			
	SNTP		nit's date and time auto-corrects when unit is connected to SNTP ser				
	USB console Mouse		s via an optional USB console (OP-87983) • Supports the assignment of the control various manus via an optional dedicated mouse (OP-				
			ble to control various menus via an optional dedicated mouse (OP-l sing the RS-232C port (Cannot be used in conjunction with RS-232				
	Touch panel	· ·	Supports dedicated touch menus and operation buttons				
			dedicated USB port (supports USB 3.0, bus-powered, rated output 9 h/Simplified Chinese/Traditional Chinese/German (initial language :				
angua aa	USB HDD	Jadanese/Englis	n/Simplified Chinese/ Iraditional Chinese/German (Initial language : expansion unit CA-DC40E/DC50E, lighting and intensity control for				
	'			and also manimization to probability.			
luminatio	n control		None				
luminatio cooling far	n control						
lluminatio Cooling far	n control Voltage Current consumption	By connecting the optional light e	None	3.1 A			
Iluminatio Cooling far Rating	n control Voltage Current consumption Operating ambient	By connecting the optional light of	None 24 VDC ±10%				
Language Illuminatio Cooling far Rating Invironmental	n control Voltage Current consumption	By connecting the optional light of	None 24 VDC ±10% 8 A				

^{*1} Positive common connections supporting NPN input devices and negative common connections supporting PNP input devices are both possible.

*2 Models equipped with the Ethernet port in the CPU unit support Ethernet port direct connection.

*3 Up to 8 light control expansion units can be connected (max. two CA-DC50E units out of 8).

■ Camera (CA-HF6400M/CA-HF6400C)

Model		CA-HF6400C	CA-HF6400M		
Image receiving element		Colour CMOS Square pixels 88× high-speed reading	Monochrome CMOS Square pixels 90× high-speed reading		
Unit cell size		2.5 µm >	< 2.5 µm		
Image size		Equivalent to 2	2" (ø32 mm)*1		
Valid pixel count		64 megapixel mode: 8192 (H) × 7808 (V) 41 megapixel mode: 7168 (H) × 5768 (V) 21 megapixel mode: 5104 (H) × 4092 (V)			
Scanning system*2		Progressive 64 megapixel mode: 59.2 ms (4 ch), 117.2 ms (2 ch), 244.1 ms (1 ch) 41 megapixel mode: 40.4 ms (4 ch), 74.7 ms (2 ch), 160.0 ms (1 ch) 21 megapixel mode: 28.9 ms (4 ch), 39.2 ms (2 ch), 83.3 ms (1 ch)	Progressive 64 megapixel mode: 57.6 ms (4 ch), 114.1 ms (2 ch), 238.5 ms (1 ch) 41 megapixel mode: 40.4 ms (4 ch), 74.6 ms (2 ch), 156.8 ms (1 ch) 21 megapixel mode: 28.9 ms (4 ch), 39.2 ms (2 ch), 83.2 ms (1 ch)		
Pixel transfer fre	quency	1085 MHz	1110 MHz		
Transfer system		Digital serial transfer			
Electronic shutte	ır	Can be set to 0.05 to 9000 msec by specifying the following numerical inputs: 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1000, 1/2000, 1/5000, 1/10000, 1/20000			
Lens mount		Special mount (M40 P0.75)*3			
Environmental	Operating ambient temperature	0 to +	40°C		
resistance	Operating ambient humidity	35 to 8	5%RH		
Weight		Approx. 350 g (no	ot including lens)		

■ Camera (CA-HF2100M/CA-HF2100C)

LumiTrax™

Model		CA-HF2100C	CA-HF2100M		
Image receiving element		Colour CMOS Square pixels 85× high-speed reading	Monochrome CMOS Square pixels 85× high-speed reading		
Unit cell size		2.5 µm × 2.5 µm			
Image size		Equivalent to ¹	1" (ø16 mm)* ¹		
Valid pixel count		21 megapixel mode: 5104 (H) × 4092 (V) 5 megapixel mode: 2432 (H) × 2050 (V)			
Scanning system*2		Progressive 21 megapixel mode: 20.2 ms (4 ch), 39.4 ms (2 ch), 83.2 ms (1 ch) 5 megapixel mode: 10.8 ms (2 ch), 23.6 ms (1 ch)	Progressive 21 megapixel mode: 20.2 ms (4 ch), 39.3 ms (2 ch), 83.2 ms (1 ch) 5 megapixel mode: 10.8 ms (2 ch), 23.5 ms (1 ch)		
Pixel transfer fre	quency	1038 MHz	1037 MHz		
Transfer system		Digital serial transfer			
Electronic shutte	ır	Can be set to 0.05 to 9000 msec by specifying the following numerical inputs: 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1000, 1/2000, 1/5000, 1/10000, 1/2000			
Lens mount		C-mount			
Environmental	Operating ambient temperature	0 to +	-40°C		
resistance	Operating ambient humidity	35 to 8	25%RH		
Weight		Approx. 380 g (no	ot including lens)		

^{*1} Equivalent to 1/2" (ø8 mm) in 5 megapixel mode. *2 Transfer time varies depending on the channel configuration.

■ Camera (CA-H500CX/H500MX)

LumiTrax™/Multi-Spectrum/LumiTrax™ specular-reflection mode/Pattern projection

Model		CA-H500CX	CA-H500MX		
Image receiving	element	Colour CMOS, 16× high-speed reading using square-pixel	Monochrome CMOS, 16× high-speed reading using square-pixel		
Unit cell size		3.45 μm >	« 3.45 µm		
Image size		Equivaler	nt to 2/3"		
Valid pixel count		5 megapixel mode: 2432 (H) × 2040 (V),	2 megapixel mode: 1600 (H) × 1200 (V),		
		Progre	essive		
Scanning system	n	5 megapixel mode: 29.2 ms	5 megapixel mode: 27.7 ms		
		2 megapixel mode: 11.7 ms			
Pixel transfer fre	quency	195 MHz			
Transfer system		Digital serial transfer			
Electronic shutte	er	Can be set to 0.017 to 100 msec by specifying the following numerical inputs: 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1000, 1/2000, 1/5000, 1/10000, 1/20000, 1/50000			
Lens mount		C-mount			
Environmental	Operating ambient temperature	0 to 4	40°C		
resistance	Operating ambient humidity	35 to 8	5%RH		
Weight		Approx. 280 g (not including lens)			

■ Camera (CA-H200CX/H200MX)

LumiTrax™/Multi-Spectrum/LumiTrax™ specular-reflection mode/Pattern projection

Model		CA-H200CX	CA-H200MX		
Image receiving	element	Colour CMOS, 16× high-speed reading using square-pixel	Monochrome CMOS, 16× high-speed reading using square-pixel		
Unit cell size		3.45 μm ×	3.45 μm		
Image size		Equivaler	nt to 1/2"		
Valid pixel count		1600 (H) ×	1200 (V)		
Scanning system	1	Progressiv	Progressive 11.7 ms		
Pixel transfer fre	quency	195 MHz			
Transfer system		Digital serial transfer			
Electronic shutte	r	Can be set to 0.017 to 100 msec by specifying the following numerical inputs: 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1000, 1/2000, 1/5000, 1/10000, 1/20000, 1/50000			
Lens mount		C-mount			
Environmental	Operating ambient temperature	0 to 40°C			
resistance	ance Operating ambient humidity 35 to 85%RH				
Weight		Approx. 280 g (not including lens)			

^{*1} Equivalent to 4/3" (ø23 mm) in 41 megapixel mode, and 1" (ø16 mm) in 21 megapixel mode. *2 Transfer time varies depending on the channel configuration.
*3 C-mount lenses can be used by replacing the lens mount on the camera with a C-mount adapter (OP-88578; sold separately). Note that 64 megapixel mode will not be supported.

Model		CA-H048CX	CA-H048MX	
Image receiving	element	Colour CMOS, 16× high-speed reading using square-pixel	Monochrome CMOS, 16× high-speed reading using square-pixel	
Unit cell size		4.8 μm ×	4.8 µm	
Image size		Equivalen	nt to 1/3"	
Valid pixel coun	t	0.47 megapixel mode: 784 (H) × 596 (V) 0.31 megapixel mode	e: 640 (H) × 480 (V) 0.24 megapixel mode: 512 (H) × 480 (V)	
Scanning system Progressive 0.47 megapixel mode: 2.9 ms 0.31 megapixel mode: 2.0 ms 0.24 megapixel mode: 1.7 ms				
Pixel transfer fre	equency	195 ľ	MHz	
Transfer system		Digital seri	al transfer	
Electronic shutte	er	Can be set to 0.022 to 1000 msec by sp 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/		
Lens mount		C-mo	ount	
Operating ambient Environmental temperature		0 to 4	0 to 40°C	
resistance	Operating ambient humidity	35 to 85%RH		
Weight		Approx. 190 g (not including lens)		

■ Camera (CA-H500C/CA-H500M)

Model		CA-H500C	CA-H500M		
Image receiving element Colour CMOS, 11×/16× high-speed reading using square-pixel Monochrome CMOS, 11×/16× high-speed reading using square			Monochrome CMOS, 11×/16× high-speed reading using square-pixel		
Unit cell size		3.45 µm ×	3.45 µm		
Image size		Equivalen	t to 2/3"		
Valid pixel coun	t	4.99 megapixels, 24	132 (H) × 2050 (V)		
Scanning syster	m	Progre: At 11× transfer speed: 61.2 ms *1,			
Pixel transfer fro	equency	At 11× transfer speed: 132 MHz (66 MHz ×	(2) *1, At 16× transfer speed: 198 MHz *2		
Transfer system		Digital seria	al transfer		
Electronic shutt	er	Can be set to 0.05 to 9000 msec by sper 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1			
Lens mount		C-mo	ount		
Enclosure rating)	IP64	1 *3		
Operating ambient temperature		0 to 5	0 to 50°C		
resistance	Operating ambient humidity	35 to 85%RH			
Weight		Approx. 75 g (not including lens)			

■ Camera (CA-H200C/CA-H200M)

Model		CA-H200C	CA-H200M	
Image receiving	element	Colour CMOS, 7x/11x/16x high-speed reading using square-pixel	Monochrome CMOS, 7x/11x/16x high-speed reading using square-pixel	
Unit cell size		4.5 μm ×	4.5 μm	
Image size		Equivalent	to 1/1.8"	
Valid pixel coun	t	2 megapixel mode: 1600 (H) × 1200 (V),	1 megapixel mode: 1024 (H) × 960 (V),	
Scanning system	n	Progressive At 7× transfer speed: 28.9 ms *1, At 16× transfer speed: 11.8 ms *2		
Pixel transfer fr	equency	At 7× transfer speed: 86 MHz (43 MHz × 2	2) *1, At 16× transfer speed: 198 MHz *2	
Transfer system	1	Digital seria	al transfer	
Electronic shutt	er	Can be set to 0.05 to 9000 msec by sper 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1		
Lens mount		C-mo	ount	
Enclosure rating)	IP64	1 *3	
Operating ambient Environmental temperature		0 to 4:	0 to 45°C	
resistance	Operating ambient humidity	35 to 85%RH		
Weight		Approx. 75 g (not including lens)		

■ Camera (CA-200C/CA-200M)

Model CA-200C CA-200M		CA-200M			
Image receiving element		Colour CMOS, High-speed reading using square-pixel	Monochrome CMOS, High-speed reading using square-pixel		
Unit cell size		4.5 μm >	4.5 μm		
Image size		Equivalen	to 1/1.8"		
Valid pixel count		2 megapixel mode: 1600 (H) × 1200 (V)	, 1 megapixel mode: 1024 (H) × 960 (V)		
Scanning system	1		Progressive 56.5 ms		
Pixel transfer fre	quency	43 M	ИНz		
Transfer system		Digital ser	al transfer		
Electronic shutte	r		Can be set to 0.05 to 9000 msec by specifying the following numerical inputs: 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1000, 1/2000, 1/5000, 1/10000, 1/2000		
Lens mount		C-m	ount		
Enclosure rating		IP6	4*1		
Operating ambient temperature		0 to	0 to 45°C		
resistance	Operating ambient humidity	35 to 85%RH			
Weight		Арргох. 75 g (по	Approx. 75 g (not including lens)		

^{*1} A KEYENCE-specified IP64-rated lens and environment-resistant cable must be used on the product.

^{*1} Transfer speed setting: Standard
*2 Transfer speed setting: Fast
*3 A KEYENCE-specified IP64-rated lens and environment-resistant cable must be used on the product.

^{*1} Transfer speed setting: Standard
*2 Transfer speed setting: Fast
*3 A KEYENCE-specified IP64-rated lens and environment-resistant cable must be used on the product.

■ Camera (CA-HS200C/CA-HS200M)

Model		CA-HS200C	CA-HS200M	
Image receiving	element	Colour CMOS, 7×/16× high-speed reading using square-pixel	Monochrome CMOS, 7×/16× high-speed reading using square-pixel	
Unit cell size		3.45 μm >	< 3.45 µm	
Image size		Equivaler	nt to 1/2"	
Valid pixel count		2 megapixel mode: 1600 (H) × 1200 (V)	, 1 megapixel mode: 1024 (H) × 960 (V)	
Scanning system	n	Progri At 7× transfer speed: 28.4 ms *1,	essive At 16× transfer speed: 14.2 ms *²	
Pixel transfer fre	quency	At 7× transfer speed: 86 MHz (43 MHz ×	2) *1, At 16× transfer speed: 198 MHz *2	
Transfer system		Digital ser	ial transfer	
Electronic shutte	er	Can be set to 0.05 to 9000 msec by spi 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/	ecifying the following numerical inputs: 1000, 1/2000, 1/5000, 1/10000, 1/20000	
Lens mount		Special mount (N	/15.5 P0.5 male)	
Operating ambient Environmental temperature		0 to	0 to 45°C	
resistance	Operating ambient humidity	35 to 85%RH		
Weight		Approx. 45 g (not including lens)		

^{*1} Transfer speed setting: Standard *2 Transfer speed setting: Fast

■ Camera (CA-H035C/CA-H035M)

Model CA-H035C CA-H035M				
Image receiving element Colour CMOS, 7x/16x high-speed reading using square-pixel Monochrome CMOS, 7x/16x high-speed reading using square			Monochrome CMOS, 7×/16× high-speed reading using square-pixel	
Unit cell size		6.9 µm ×	: 6.9 µm	
Image size		Equivalen	nt to 1/3"	
Valid pixel coun		0.31 megapixel mode: 640 (H) × 480 (V),	0.24 megapixel mode: 512 (H) × 480 (V)	
Scanning syster	n	Progre At 7× transfer speed: 4.8 ms *1, /		
Pixel transfer fre	equency	At 7× transfer speed: 86 MHz (43 MHz × 1	2) *1, At 16× transfer speed: 198 MHz *2	
Transfer system		Digital seri	al transfer	
Electronic shutte	er	Can be set to 0.05 to 9000 msec by spe 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1		
Lens mount		C-ma	ount	
Enclosure rating		IP64	4*3	
Operating ambient temperature		0 to 5	0 to 50°C	
resistance	Operating ambient humidity	35 to 85%RH		
Weight	·	Approx. 75 g (not	t including lens)	

■ Camera (CA-035C/CA-035M)

Model		CA-035C CA-035M		
Image receiving element		Colour CMOS, High-speed reading using square-pixel	Monochrome CMOS, High-speed reading using square-pixel	
Unit cell size		6.9 µm >	6.9 μm	
Image size		Equivaler	nt to 1/3"	
Valid pixel coun	t	0.31 megapixel mode: 640 (H) × 480 (V),	0.24 megapixel mode: 512 (H) × 480 (V)	
Scanning system	m	Progra 16.5		
Pixel transfer fre	equency	25 N	ИНz	
Transfer system		Digital seri	al transfer	
Electronic shutte	er	Can be set to 0.05 to 9000 msec by specifying the following numerical inputs: 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/1000, 1/2000, 1/5000, 1/10000, 1/20000		
Lens mount		C-m	ount	
Enclosure rating		IP6	4*1	
Environmental	Operating ambient temperature 0 to 50°C		50°C	
resistance	Operating ambient humidity	35 to 85%RH		
Weight		Approx. 75 g (no	t including lens)	

^{*1} A KEYENCE-specified IP64-rated lens and environment-resistant cable must be used on the product.

■ Camera (CA-HS035C/CA-HS035M)

Madal	Camera unit	CA-HS035CH	CA-HS035MH		
Model	Relay unit	CA-HS035CU	CA-HS035MU		
Image receivii	ng element	Colour CMOS, 7× high-speed reading using square-pixel	Monochrome CMOS, 7× high-speed reading using square-pixel		
Unit cell size		7.4 µm >	· 7.4 μm		
Image size		Equivaler	nt to 1/3"		
Valid pixel cou	unt	0.31 megapixel mode: 640 (H) × 480 (V),	0.24 megapixel mode: 512 (H) × 480 (V)		
Scanning syst	tem		Progressive 4.5 ms		
Pixel transfer	frequency	86 MHz (43	86 MHz (43 MHz × 2)		
Transfer syste	em	Digital serial transfer			
Electronic shu	utter	Can be set to 0.05 to 100 msec by spe 1/15, 1/30, 1/60, 1/120, 1/240, 1/500, 1/			
Lens mount		Special mount (N	M10.5 P0.5 male)		
Environmenta	Operating ambient temperature	0 to 4	0 to 40°C		
resistance	Operating ambient humidity	35 to 85%RH			
Weight	Camera unit	Approx. 135 g (cable incl	luded, lens not included)		
vveigiit	Relay unit	Approx. 75 g (not including lens)			

^{*1} Transfer speed setting: Standard
*2 Transfer speed setting: Fast
*3 A KEYENCE-specified IP64-rated lens and environment-resistant cable must be used on the product.

■ High-speed transmission line scan camera (CA-HL02MX/HL04MX/HL08MX)

Model		CA-HL	.02MX	CA-HL04MX		CA-HL08MX		
Image receiving element			mm monochrome CMOS image receiving element, $30 \times$ high-speed reading using square-pixel $32 \times$ high-speed reading using square-pixel			30.8 mm monochrome CMOS image receiving element, 64× high-speed reading using square-pixel		
Unit cell size		15 μm × 7.5 μm*1	7.5 µm × 7.5 µm	15 μm × 7.5 μm*1	7.5 μm × 7.5 μm	3.75 μm × 3.75 μm	7.5 µm × 7.5 µm	3.75 µm × 3.75 µm
Valid pixel count Processing area (individual) Processing area (continuous)		1024 pixels 1024 (H) × 16384 (L) 1024 (H) × 8192 (V)	2048 pixels 2048 (H) × 16384 (L) 2048 (H) × 8192 (V)		2048 pixels 2048 (H) × 16384 (L) 2048 (H) × 8192 (V)		4096 pixels 4096 (H) × 16384 (L) 4096 (H) × 8192 (V)	8192 pixels 8192 (H) × 8192 (L) 8192 (H) × 8192 (V)
Minimum scan	time	6.1 µs (10	65 kHz)*2	6.1 μs (165 kHz)*2 10.		10.2 μs (97.7 kHz)*2	6.1 μs (165 kHz)*2	10.2 μs (97.7 kHz)*2
	LumiTrax (in specular reflection mode)	48.5 µs (2	0.6 kHz)*2	48.5 µs (2	20.6 kHz)*2	81.9 μs (12.2 kHz)*2	48.5 μs (20.6 kHz)*2	81.9 µs (12.2 kHz)*2
Pixel transfer fr	requency	188 MHz, 15×	375 MHz, 30×	188 MHz, 15×	375 MHz, 30×	400 MHz, 32×	750 MHz, 60×	800 MHz, 64×
Transfer system	n	Digital serial transfer						
Electronic shut	ter		User-defined settings (2 µs	to 20000 μs, max. shu	itter speed limited to 4	µsec less than line sca	ın interval during operation)	
				Shading correction (setting saved in camera)				
Function		Installation auxiliary function (LED pointer / Mounting angle monitor)						
		Binning function						
Lens mount		C-m	ount		C-mount		Special moun	t (M40 P0.75)
Environmental	Ambient temperature	0 to 40°C						
resistance	Ambient humidity	35 to 85% RH (No condensation)					·	
Weight		Approx. 350 g (no	ot including lens)	Appro	x. 350 g (not includin	g lens)	Approx. 310 g (n	ot including lens)

^{*1} When using the binning function to use information from multiple image receiving elements for individual pixel data.

■ XT camera

Model		XT-024	XT-060	
IVIOUEI		24 mm type	60 mm type	
Image sensor		Monochrome CN	IOS image sensor	
Image size (3D))	3072 × 3072 (1536 × 1536) pixels	3072 × 3072 (1536 × 1536) pixels	
	XY data interval	7.85 μm (15.7 μm)	19.6 µm (39.2 µm)	
Image size (2D)		3072 × 3072 (1536 × 1536) pixels	3072 × 3072 (1536 × 1536) pixels	
	XY data interval	7.85 μm (15.7 μm)	19.6 µm (39.2 µm)	
XYZ repeatabilit	ty (σ)*1	0.5 μm*²	1 μm*²	
Measurement	Height difference	±10 μm*³	±20 μm*³	
accuracy	Width	±10 μm*3	±20 μm*³	
Shutter speed 50 µs to 200 ms			50 μs to 200 ms	
XY field of view	Near/Reference distance/Far	24.1 × 24.1 mm	60.2 × 60.2 mm	
Z range (from r	eference distance)	±2 mm	±6 mm	
WD (to standard	d surface)	200	mm	
Light source		LED (red, green, blue); Individua	ally configurable up to 100 steps	
Connection		XG-X290	00/X2800	
Display	LED display	Power supply,	Operation mode	
Rating	Power voltage	24 VD0	C ±10%	
Current consumption		3 A		
Environmental	Operating ambient temperature	0 to	40°C	
resistance	Operating ambient humidity	20 to 85% RH (no condensation)		
Dimensions		286 × 286 × 286 mm		
Weight		9.7 kg	10.1 kg	

^{*1} When using an averaging filter (3 x 3) and a KEYENCE standard workpiece (binning ON). *2 Repeatability at centre of field of view ((60 mm type) Centre: 30 x 30 mm, (24 mm type) Centre: 12 x 12 mm).

■ XR camera

Model		XR-HT15M	XR-HT40M	XR-HT15MD	XR-HT40MD		
Image sensor		Monochrome CMOS image receiving element					
Image size in pixe	els* ⁵	1408 × 1408 (704 × 704)	2048 × 2048 (1024 × 1024)	1408 × 1408 (704 × 704)	2048 × 2048 (1024 × 1024)		
Shutter speed		50 μs to 200 ms	50 μs to 200 ms	50 μs to 200 ms	50 μs to 200 ms		
Reference distant	ce		84	mm			
	OV during XY normalisation)	12.3 × 12.3 mm (12.5 mm)	33.9 × 33.9 mm (35.0 mm)	12.3 × 12.3 mm (12.5 mm)	33.9 × 33.9 mm (35.0 mm)		
Field of view XY	ce distance	12.5 × 12.5 mm	35.5 × 35.5 mm	12.5 × 12.5 mm	35.5 × 35.5 mm		
Far		12.6 × 12.6 mm	37.0 × 37.0 mm	12.6 × 12.6 mm	37.0 × 37.0 mm		
Z range (from ref	erence distance)	±1.5 mm	±5 mm	±1.5 mm	±5 mm		
Repeatability (σ)	X, Y, Z	1 μm*1	2 μm*1	1 μm*1	2 μm*1		
Data interval X, Y	,	9.5 µm (19 µm)	18.5 µm (37 µm)	9.5 µm (19 µm)	18.5 μm (37 μm)		
Light source		LED (blue, red)					
Connected to		XG-X2800(P)) + CA-E100T	1000Base-T-compliant	'C and Ethernet card*2		
Image transfer m	ethod	Digital serial transfer		GigE Vision™			
Rating	Power supply voltage	-		24 V ±10%			
natility	Current consumption		-	1.2 A*3			
Functions		Image capture functions (height image, greyscale image), auxiliary functions (cross mark display, reference plane correction, 3D calibration)					
	Ambient temperature*4	0°C to 40°C					
Environmental	Ambient humidity	35 to 85% RH (no condensation)					
resistance	Vibration resistance		10 to 57 Hz: 0.75 mm p-p, 57 to 500 Hz: 5G, in X, Y, and Z directions, 3 hours respectively				
Impact resistance		15 G/6 msec					
Dimensions			250.5 × 120	0.5 × 54 mm	·		
Weight		Approx. 2.5 kg	Approx. 2.4 kg	Approx. 2.5 kg	Approx. 2.4 kg		

^{*1} Value for KEYENCE standard plane workpieces when binning is ON and a 3 x 3 average filter is used once. "2 •1000Base-T-compliant PC and network card (NIC) are required. Intel® Gigabit Server Adapter or its equivalent is recommended. •Connections to LANs and connections through a switch or router are not covered under warranty. By using multiple network cards, up to 4 cameras can be simultaneously connected to 1 PC unit. "3 Steady state value. Select a power supply with sufficient capacity by taking inrush current into consideration. "4 0°C to 35°C in unidirectional light projection mode and when the trigger interval is not more than twice as long as the total exposure time. "5 Value in parentheses is with Binning ON.

Environment for running the software development kit for the PC connection model Microsoft Windows 7 Home Premium, Professional, Ultimate, Enterprise

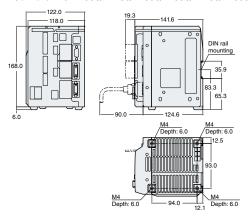
- For all operating systems, only Japanese and English versions are supported. Supports the 64-bit version of Microsoft Windows 7 only. For all other operating systems, only the 32-bit version is supported.
- Cannot be used on operating systems not listed above. CPU: Recommended: Intel Core-i5 2.5 GHz or higher NAM: Recommended: 4 GB or higher Video card: Required: Card compliant with DirectX9.0c or later, Video memory: 64 MB or more Microsoft and Windows are either registered trademarks or trademarks of Microsoft Corporation in the United States and/or other countries.

^{*2} When the line scan interval is configured for use with an encoder. When time-specified, the scan time may be lengthened by up to 1 µsec.

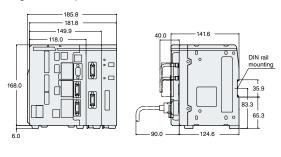
^{*3} Using a KEYENCE height difference gauge. [60 mm type] Height difference: 2 mm/Width: 20 mm; [24 mm type] Height difference: 1 mm/Width: 10 mm

Controller

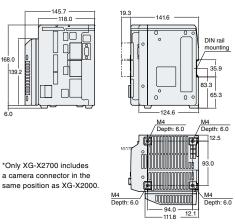
■Controller XG-X2000/X2200/X2500/X1000/X1200/X1500



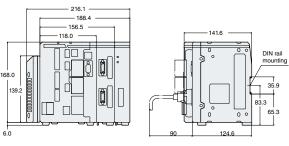
■When mounting area camera input unit CA-E100/ Light control expansion module CA-DC40E



■Controller XG-X2700*/X2800/X2900

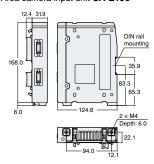


■ When mounting line scan camera input unit CA-E100L*/CC-Link unit CA-NCL20E/ EtherCAT® unit CA-NEC20E/PROFINET module CA-NPN20E/EtherNet/IP® module CA-NEP20E

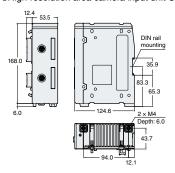


*CA-E100L can only be connected to XG-X2800.

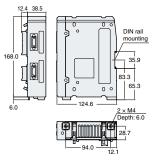
■Area camera input unit CA-E100



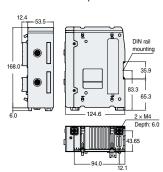
■ High-resolution area camera input unit CA-E200



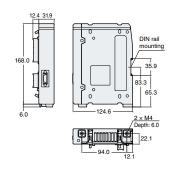
■ Line scan camera input unit CA-E100L



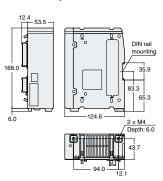
■ Line scan camera input unit CA-E200L



■XR camera input unit CA-E100T

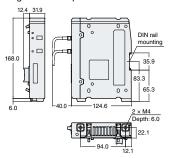


■XT camera input unit CA-E200T

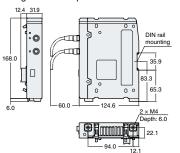


Controller

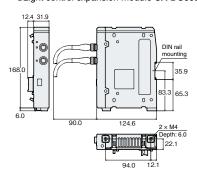
■Light control expansion module CA-DC40E



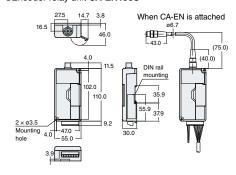
■ Light control expansion module CA-DC50E



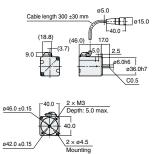
■ Light control expansion module CA-DC60E



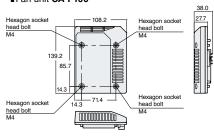
■Encoder relay unit CA-EN100U



■Dedicated encoder CA-EN100H



■Fan unit CA-F100

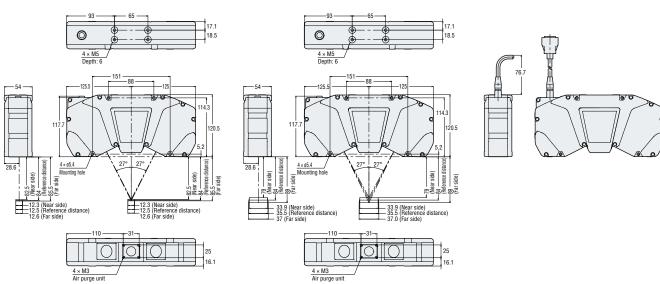


XR camera

■ Camera XR-HT15M

■ Camera XR-HT40M

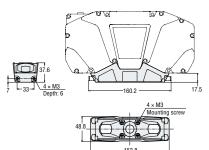
■ With CA-CHx cable



E Camera XR-HT15MD E Camera XR-HT40MD E Camera XR-HT40MD E With CA-CDx/CA-CPx cables Fig. 17.1 Fig. 18.5 Fig. 18.5

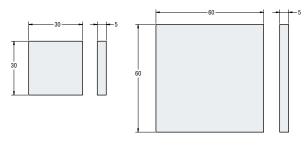
XR air purge unit

■ Air purge unit XR-AP1



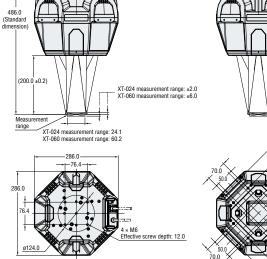
XR calibration targets

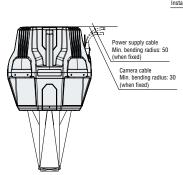
■ For XR-HT15M(D): **OP-87740** ■ For XR-HT40M(D): **OP-87741**

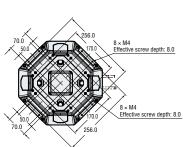


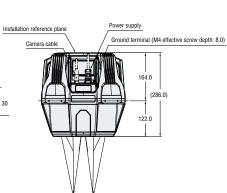
XT camera





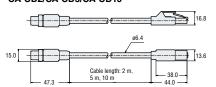




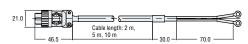


XT/XR cable

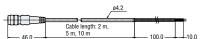
■ XT cable/PC connection cable for XR CA-CD2/CA-CD5/CA-CD10



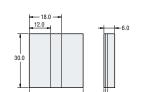
■ XT power supply cable **OP-88356/OP-88357/OP-88358**



■ XR power supply cable CA-CP2/CA-CP5/CA-CP10

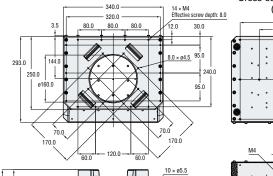


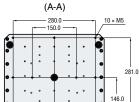
XT/XR height difference gauge ■ Height difference gauge OP-87742



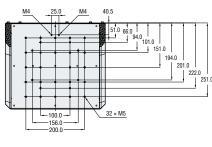
Dedicated stand for XT camera

■ OP-88427



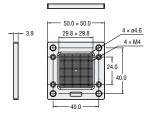


Cross-sectional view

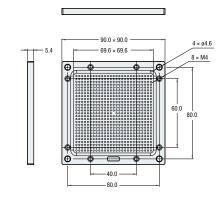


XT calibration target

■ OP-88400



■ OP-88401

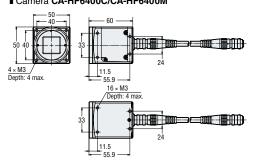


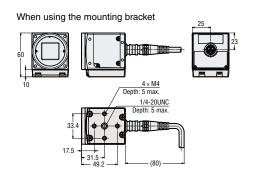
Camera

(484.0)

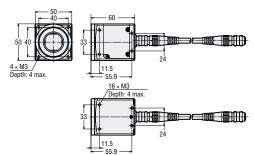
470.0

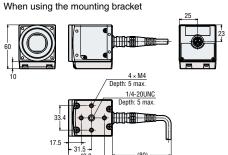
■ Camera CA-HF6400C/CA-HF6400M



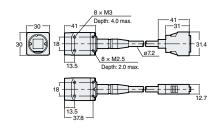


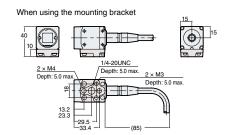
■ Camera CA-HF2100C/CA-HF2100M



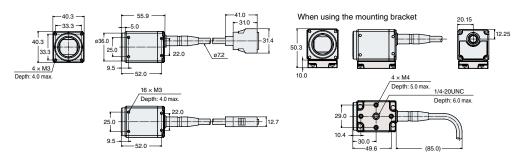


■Camera CA-H500C/CA-H500M/CA-H200C/CA-H200M/CA-200C/CA-200M/CA-H035C/CA-H035M/CA-035C/CA-035M

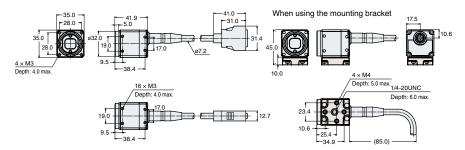




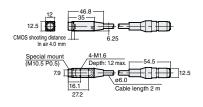
■ Camera CA-H500CX/CA-H500MX/CA-H200CX/CA-H200MX

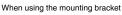


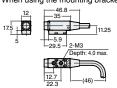
■Camera CA-H048CX/CA-H048MX



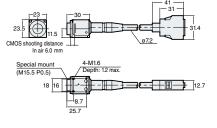
■Camera CA-HS035CH/CA-HS035MH

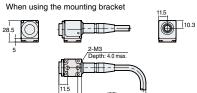




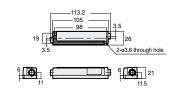


■Camera CA-HS200C/CA-HS200M

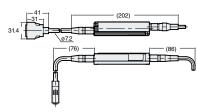




■ Camera control unit CA-HS035CU/CA-HS035MU

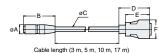


With cable connected



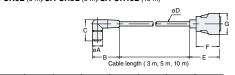
■ Camera cable CA-CH3 (3 m)/CA-CH5 (5 m)/CA-CH10 (10 m)





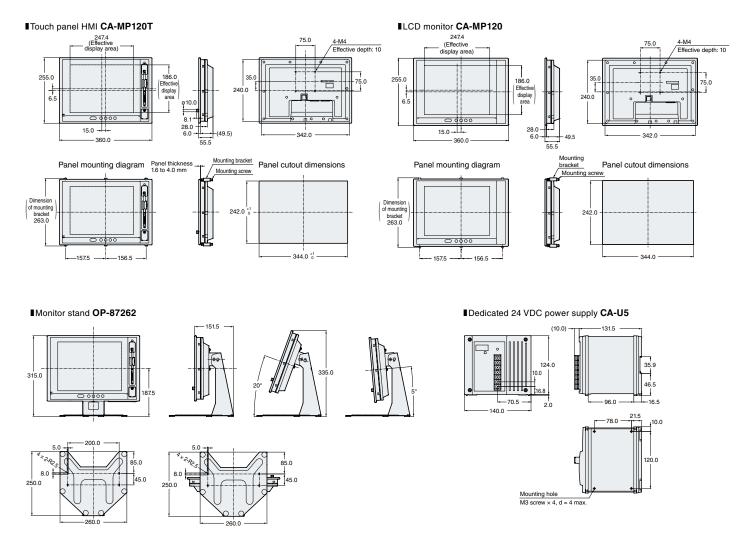
	Α	В	С	D	E	F
CA-CHx	12.5	43.0	7.2	41.0	31.0	31.4
CA-CHxR	14.0	54.0	7.6	41.0	31.0	31.4

■ L-shaped connector camera cable CA-CH3L (3 m)/CA-CH5L (5 m)/CA-CH10L (10 m)



	Cable length (3 m, 5 m, 10 m)						
	Α	В	С	D	Е	F	G
CA-CHxL	14.0	38.0	30.0	7.2	41.0	31.0	31.4

■ High-speed line scan camera CA-HL02MX/HL04MX ■High-speed line scan camera cable When using the mounting bracket CA-CF3(3 m)/CA-CF5(5 m)/CA-CF10(10 m) ø6.8 Cable length (3 m, 5 m, 10 m) Max. 20 m (10 m + extension cable 10 m) - 39.8 -58.2 Depth: 5.0 1/4-20UNC ■L-shaped connector cable for high-speed line scan cameras CA-CF3L(3 m)/CA-CF5L(5 m)/CA-CF10L(10 m) ø6.8 Cable length (3 m, 5 m) Max. 20 m (10 m + exte ■ High-speed line scan camera CA-HL08MX When using the mounting bracket 4 × ø3.0 Depth: 5.0 ø14.0 5.0 16 × ø3.0 Depth: 5.0 - 44.0 (80.0)



Refer to the Vision System Peripheral Equipment catalogue for dimension diagrams for lenses and close-up rings.

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